

SOLUTION 1.

In binary hypothesis testing, the statistic $T(\mathbf{Y})$ is a sufficient if and only if the log-likelihood ratio can be specified by $T(\mathbf{Y})$. For our problem, the log-likelihood ratio is given by

$$\log \left(\frac{p_H(1)f_{\mathbf{Y}|H}(\mathbf{y} | H = 1)}{p_H(0)f_{\mathbf{Y}|H}(\mathbf{y} | H = 0)} \right) = -\frac{n}{2} \log(2) + \log \left(\frac{p_H(1)}{p_H(0)} \right) + \sum_{i=1}^n \frac{y_i^2}{4}.$$

Therefore, for each of the proposed statistics, we need to see if it fully determines the value of the log-likelihood ratio. Going in this direction, we have:

- (a) $T_1(\mathbf{Y}) = \sum_i Y_i$. (Not a sufficient statistic)
- (b) $T_2(\mathbf{Y}) = \sum_i Y_i^2$. (Sufficient statistic)
- (c) $T_3(\mathbf{Y}) = \sum_i |Y_i|$. (Not a sufficient statistic)
- (d) $T_4(\mathbf{Y}) = \max_i |Y_i|$. (Not a sufficient statistic)

SOLUTION 2.

- (a) The variable \tilde{Y} is a sufficient statistic. We can perform Fisher-Neyman factorization on the output conditional probability density function :

$$\begin{aligned} f_{Y_1, Y_2 | H}(y_1, y_2 | i) &= \frac{1}{2\pi\sigma^2} \exp \left(-\frac{(y_1 - a_i)^2 + (y_2 + a_i)^2}{2\sigma^2} \right) \\ &= \exp \left(\frac{a_i}{\sigma^2} (y_1 - y_2 - a_i) \right) \left(\frac{1}{2\pi\sigma^2} \exp \left(-\frac{1}{2\sigma^2} (y_1^2 + y_2^2) \right) \right) \end{aligned}$$

Using the Fisher-Neyman Factorization Theorem, we see that

$$\begin{aligned} T(y_1, y_2) &= y_1 - y_2 \\ g_i(x) &= \exp \left(\frac{a_i}{\sigma^2} (x - a_i) \right) \\ h(y) &= \frac{1}{2\pi\sigma^2} \exp \left(-\frac{1}{2\sigma^2} (y_1^2 + y_2^2) \right) \end{aligned}$$

- (b) The variable \tilde{Y} can also be written as,

$$\tilde{Y} = 2a_i + \underbrace{Z_1 - Z_2}_{\tilde{Z}}.$$

The noise term \tilde{Z} will have a Gaussian distribution with variance $2\sigma^2$. We can compare it with the new observation given in the problem, $2U$ (note that scaling does not change the error probability),

$$2U = 2a_i + 2W$$

The noise term $2W$ is Gaussian distributed with variance $\frac{4\sigma^2}{3}$. We can see that both noise terms are Gaussian distributed with the noise term in $2U$ having smaller variance. Therefore, we should choose the new observation U .

SOLUTION 3.

(a) The log-likelihood ratio is given by

$$\log \left(\frac{f_{Y|H}(y|H=1)}{f_{Y|H}(y|H=0)} \right) = |y-1| - |y+1|.$$

Due to assumption of equally-likely hypotheses, the following decision rule minimizes the error probability,

$$|y-1| - |y+1| \underset{\hat{H}=0}{\overset{\hat{H}=1}{\gtrless}} 0,$$

which is equivalent to

$$y \underset{\hat{H}=1}{\overset{\hat{H}=0}{\gtrless}} 0.$$

(b) For the optimal decision rule we computed in (a), the decision boundary is given by $y = 0$. We can calculate the probability of error given $H = 1$ as

$$P(\hat{H} = 0 | H = 1) = \int_1^\infty \frac{1}{2} \exp(-y) dy = \frac{e^{-1}}{2}.$$

By symmetry we have the error probability $P_e = P(\hat{H} = 0 | H = 1) = P(\hat{H} = 1 | H = 0)$.

(c) The Bhattacharyya bound is given by

$$\begin{aligned} P_e &\leq \int_{-\infty}^{\infty} \sqrt{f_{Y|H}(y|H=0) f_{Y|H}(y|H=1)} dy \\ &= \frac{1}{2} \int_{-\infty}^{\infty} \exp \left(-\frac{|y-1| + |y+1|}{2} \right) dy. \end{aligned}$$

The exponent can be represented as a piecewise linear function

$$-\frac{|y-1| + |y+1|}{2} = \begin{cases} y & y < -1 \\ -1 & -1 \leq y \leq 1 \\ -y & y > 1. \end{cases}$$

We divide the integration region according to these intervals such that we have

$$\begin{aligned} P_e &\leq \frac{1}{2} \left(\int_{-\infty}^{-1} e^y dy + \int_{-1}^1 e^{-1} dy + \int_1^{\infty} e^{-y} dy \right) \\ &= \frac{1}{2} (e^{-1} + 2e^{-1} + e^{-1}) \\ &= 2e^{-1}. \end{aligned}$$