

Robust strategies, pathwise Itô calculus, and generalized Takagi functions

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In mainstream finance, the price evolution of a risky asset is usually modeled as a stochastic process defined on some probability space.

Problem

- only one single trajectory of the asset price process is observable
- there are no repeated “experiments”
- the price evolution typically lacks stationarity

It follows that the law of the stochastic process cannot be measured accurately by means of statistical observation. We are facing **model ambiguity**.

Practically important consequence: **model risk**

Occam’s razor: do without a probability space

1. Continuous-time finance without probability

Let X_t , $0 \leq t \leq T$, be the price evolution of a risky asset. We assume for simplicity that X is a continuous function and that there is a riskless asset with prices $B_t = 1$.

Trading strategy (ξ, η) :

- ξ_t shares of the risky asset
 - η_t shares of the riskless asset
- at time t .

Portfolio value at time t :

$$V_t = \xi_t X_t + \eta_t$$

Key notion for continuous-time finance: self-financing strategy

If trading is only possible at times $0 = t_0 < t_1 < \cdots < t_N = T$, a strategy (ξ, η) is self-financing if and only if

$$(1) \quad V_{t_i} = V_0 + \sum_{k=1}^i \xi_{t_{k-1}} (X_{t_k} - X_{t_{k-1}}), \quad i = 1, \dots, N$$

Now let $(\mathbb{T}_n)_{n \in \mathbb{N}}$ be a refining sequence of partitions (i.e., $\mathbb{T}_1 \subset \mathbb{T}_2 \subset \cdots$ and $\text{mesh}(\mathbb{T}_n) \rightarrow 0$). Then (ξ, η) can be called self-financing if we may pass to the limit in (1). That is,

$$V_t = V_0 + \int_0^t \xi_s dX_s, \quad 0 \leq t \leq T,$$

where the integral should be understood as the limit of the corresponding Riemann sums:

$$\int_0^t \xi_s dX_s = \lim_{n \uparrow \infty} \sum_{s \in \mathbb{T}_n, s \leq t} \xi_s (X_{s'} - X_s)$$

(Here, s' denotes the successor of s in \mathbb{T}_n).

A special strategy

Here we give a version of an argument from Föllmer (2001)

Proposition 1. *For $K \in \mathbb{R}$ let*

$$\xi_t = 2(X_t - K) \quad 0 \leq t \leq T.$$

Then $\int_0^t \xi_t dX_t$ exists for all t as the limit of Riemann sums if and only if the quadratic variation of X ,

$$\langle X \rangle_t := \lim_{N \uparrow \infty} \sum_{s \in \mathbb{T}_N, s \leq t} (X_{s'} - X_s)^2,$$

exists for all t . In this case

$$\int_0^t \xi_s dX_s = (X_t - K)^2 - (X_0 - K)^2 - \langle X \rangle_t$$

For $K = X_0$

Proposition 1. *Let*

$$\xi_t = 2(X_t - X_0), \quad 0 \leq t \leq T.$$

Then $\int_0^t \xi_t dX_t$ exists for all t as the limit of Riemann sums if and only if the quadratic variation of X ,

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exists for all t . In this case

$$\int_0^t \xi_s dX_s = (X_t - X_0)^2 - \langle X \rangle_t$$

We always have $\langle X \rangle_t = 0$ if X is of bounded variation or Hölder continuous for some exponent $\alpha > 1/2$ (e.g., fractional Brownian motion with $H > 1/2$)

Otherwise, the quadratic variation $\langle X \rangle$ depends strongly on the choice of (\mathbb{T}_n) .

Indeed, for instance it is well known that for any continuous function X there exists a refining sequence of partitions along which $\langle X \rangle_t = 0$ (e.g., Freedman (1983))

If $\langle X \rangle_t$ exists and is continuous in t , Itô's formula holds in the following strictly pathwise sense (Föllmer 1981):

$$f(X_t) - f(X_0) = \int_0^t f'(X_s) dX_s + \frac{1}{2} \int_0^t f''(X_s) d\langle X \rangle_s$$

where

$$\int_0^t f'(X_s) dX_s = \lim_{n \uparrow \infty} \sum_{s \in \mathbb{T}_n, s \leq t} f'(X_s)(X_{s'} - X_s)$$

is sometimes called the Föllmer integral and $\int_0^t f''(X_s) d\langle X \rangle_s$ is a standard Riemann Stieltjes integral.

This formula was extended by Dupire (2009) and Cont & Fournié (2010) to a functional context.

Incomplete list of financial applications of pathwise Itô calculus

- Strictly pathwise approach to Black–Scholes formula (Bick & Willinger 1994)
- Robustness of hedging strategies and pricing formulas for exotic options (A.S. & Stadjé 2007, Cont & Riga 2015)
- Model-free replication of variance swaps (e.g., Davis et al. (2010))
- CPPI strategies (A.S. 2014)
- Functional and pathwise extension of the Fernholz–Karatzas stochastic portfolio theory (A.S., Speiser & Voloshchenko 2015)

The key to many of these results is the following [associativity property](#) of the Föllmer integral:

$$\int_0^t \eta_s d\left(\int_0^s \xi_r dX_r\right) = \int_0^t \eta_s \xi_s dX_s$$

(A.S. 2014, A.S. & Voloshchenko 2015)

2. In search of a class of test integrators

Let's fix the sequence of dyadic partitions,

$$\mathbb{T}_n := \{k2^{-n} \mid k = 0, \dots, 2^n\}, \quad n = 1, 2, \dots$$

Goal: Find a rich class of functions $x \in C[0, 1]$ that admit a nontrivial continuous quadratic variation along (\mathbb{T}_n) .

Of course this is true for the sample paths of Brownian motion or other continuous semimartingales—as long as these sample paths do not belong to a certain nullset A .

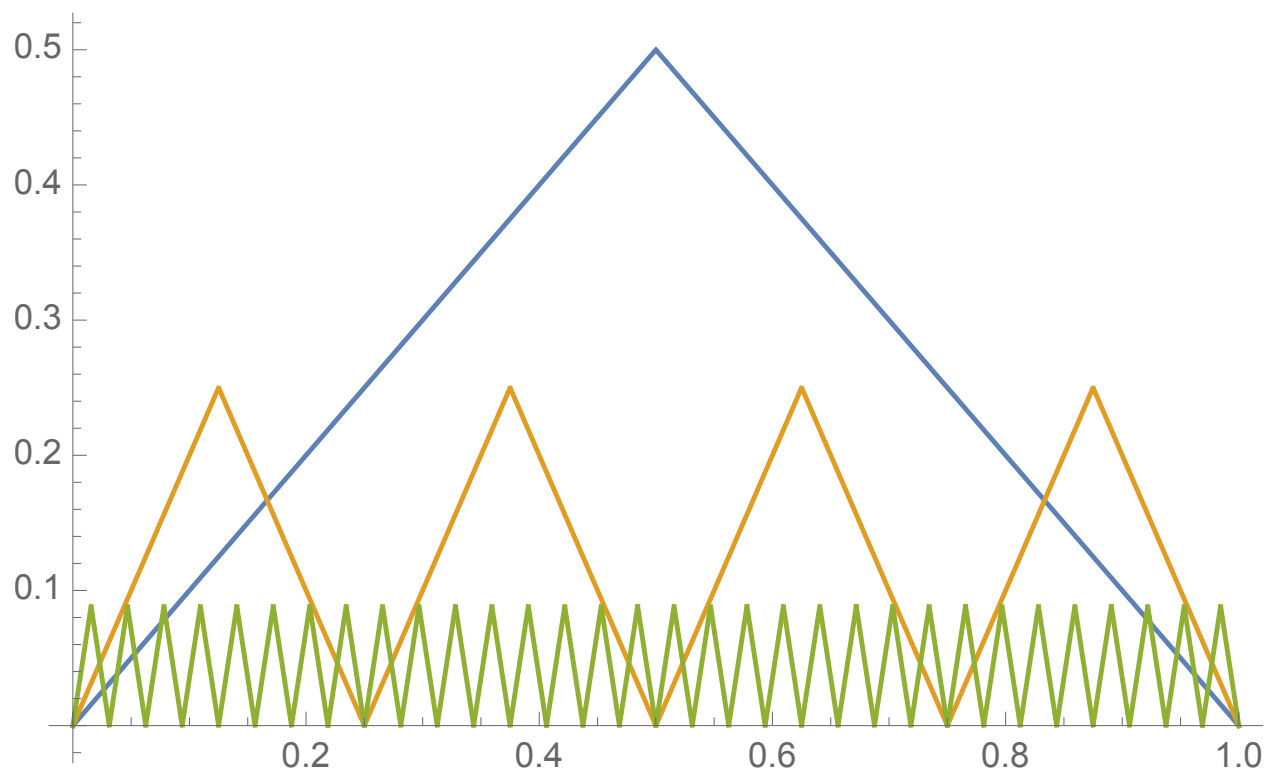
But A is not explicit, and so it is not possible to tell whether a specific realization x of Brownian motion does indeed admit the quadratic variation $\langle x \rangle_t = t$ along $(\mathbb{T}_n)_{n \in \mathbb{N}}$.

Moreover, this selection principle for functions x lets a probabilistic model enter through the backdoor...

A result of N. Gantert

Recall that the *Faber–Schauder functions* are defined as

$$e_{0,0}(t) := (\min\{t, 1 - t\})^+ \quad e_{m,k}(t) := 2^{-m/2} e_{0,0}(2^m t - k)$$



Functions $e_{n,k}$ for $n = 0$, $n = 2$, and $n = 5$

Every function $x \in C[0, 1]$ with $x(0) = x(1) = 0$ can be represented as

$$x = \sum_{m=0}^{\infty} \sum_{k=0}^{2^m-1} \theta_{m,k} e_{m,k}$$

where

$$\theta_{m,k} = 2^{m/2} \left(2x\left(\frac{2k+1}{2^{m+1}}\right) - x\left(\frac{k}{2^m}\right) - x\left(\frac{k+1}{2^m}\right) \right).$$

Gantert (1991, 1994) showed that

$$\langle x \rangle_t^n := \sum_{s \in \mathbb{T}_n, s \leq t} (x(s') - x(s))^2$$

can be computed for $t = 1$ as

$$\langle x \rangle_1^n = \frac{1}{2^n} \sum_{m=0}^{n-1} \sum_{k=0}^{2^m-1} \theta_{m,k}^2$$

By letting

$$\mathcal{X} := \left\{ x \in C[0, 1] \mid x = \sum_{m=0}^{\infty} \sum_{k=0}^{2^m-1} \theta_{m,k} e_{m,k} \text{ for coefficients } \theta_{m,k} \in \{-1, +1\} \right\}$$

(which is easily shown to be possible) we hence get a class of functions with $\langle x \rangle_1 = 1$ for all $x \in \mathcal{X}$.

As a matter of fact:

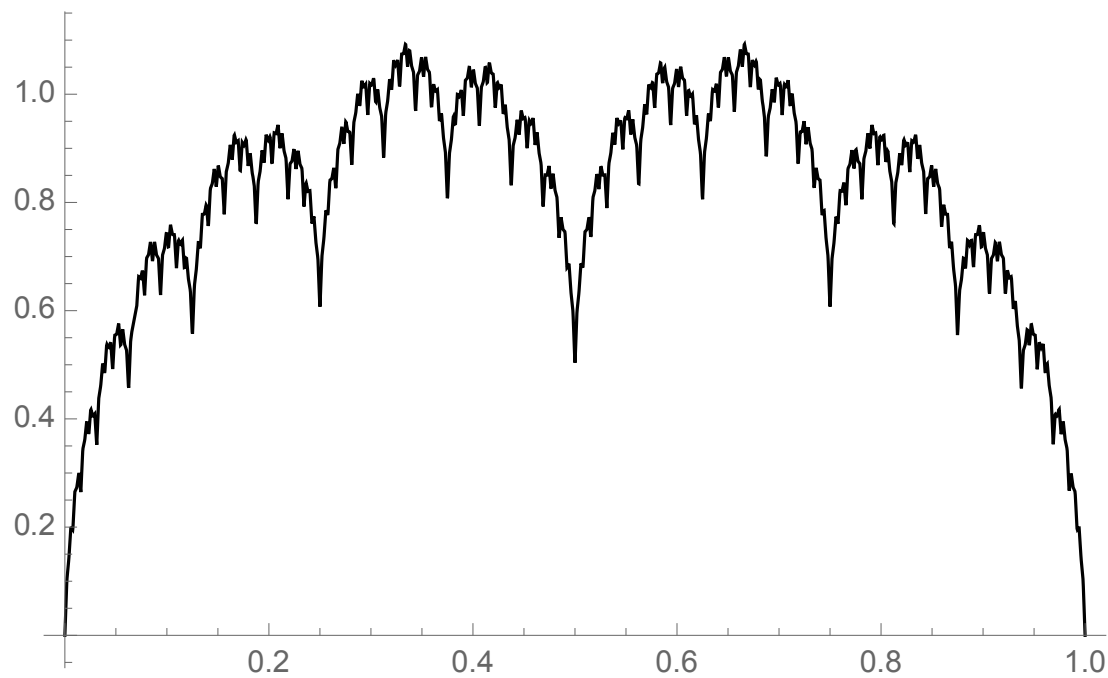
Proposition 2. *Every $x \in \mathcal{X}$ has the quadratic variation $\langle x \rangle_t = t$ along (\mathbb{T}_n) .*

Link to the Takagi function and its generalizations

The specific function

$$\widehat{x} := \sum_{m=0}^{\infty} \sum_{k=0}^{2^m-1} e_{m,k}$$

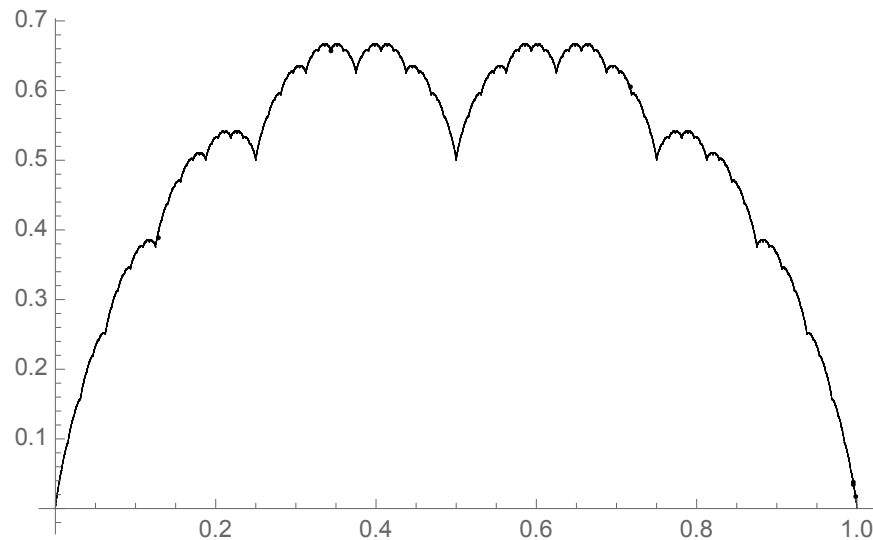
has some interesting properties.



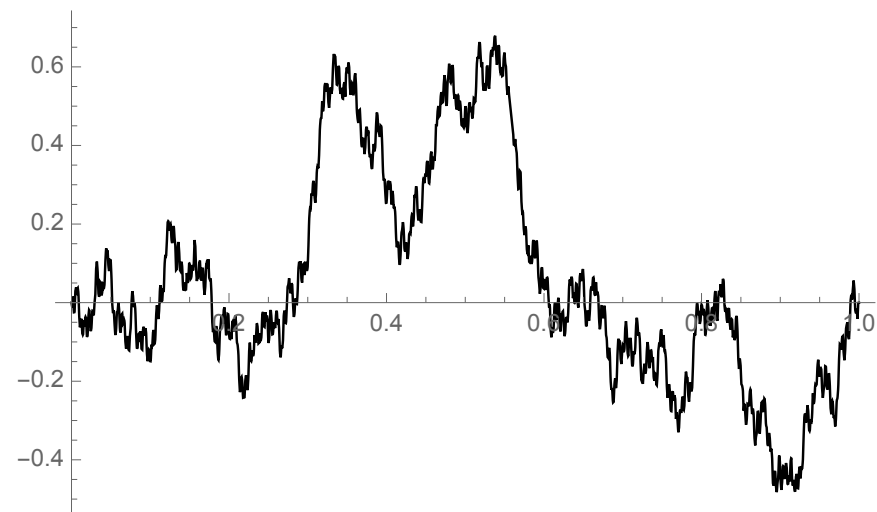
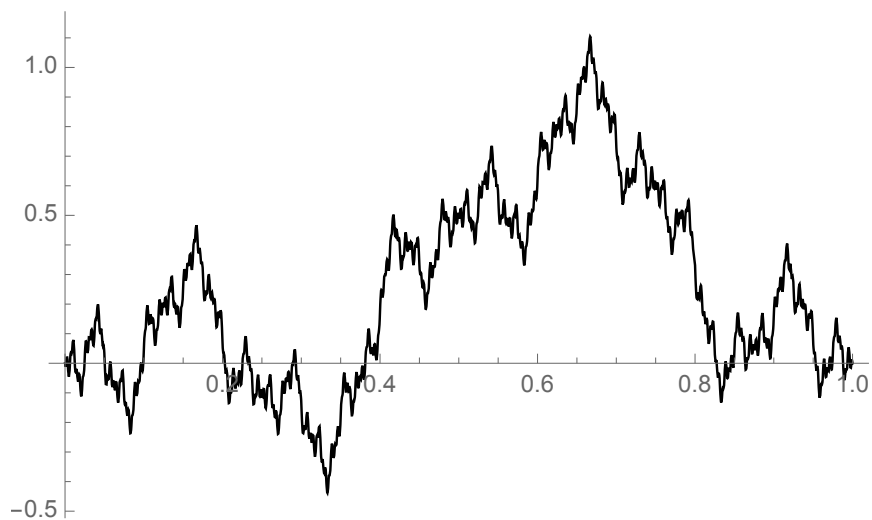
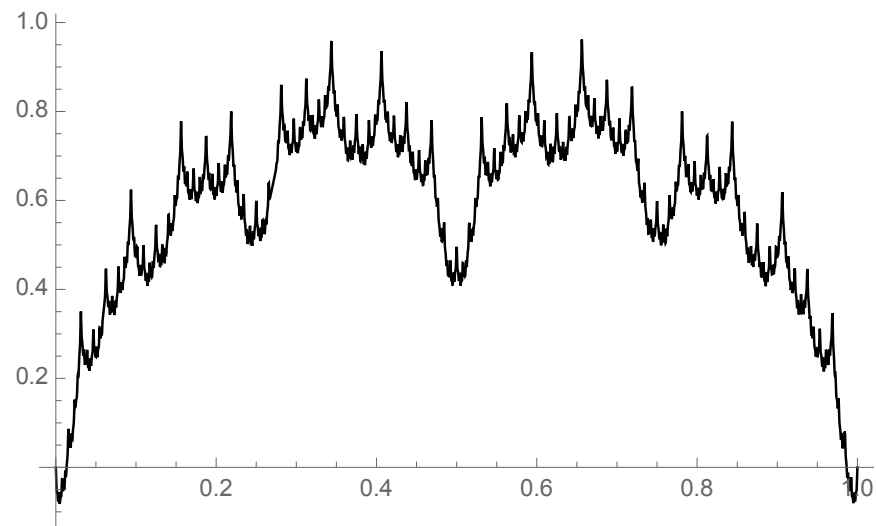
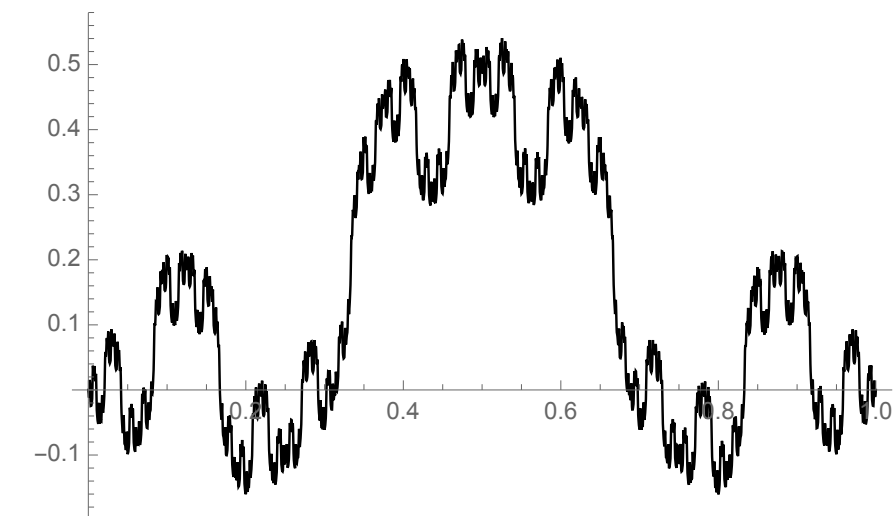
The function \hat{x} is closely related to the celebrated [Takagi function](#),

$$\tau = \sum_{m=0}^{\infty} \sum_{k=0}^{2^m-1} 2^{-m/2} e_{m,k}$$

which was first found by Takagi (1903) and rediscovered many times (e.g., by van der Waerden (1930), Hildebrandt (1933), Tambs–Lyche (1942), and de Rham (1957))

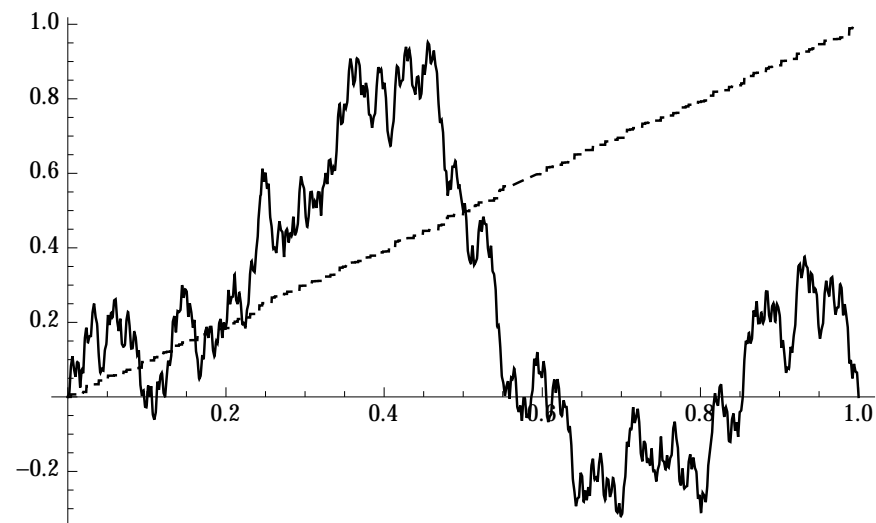
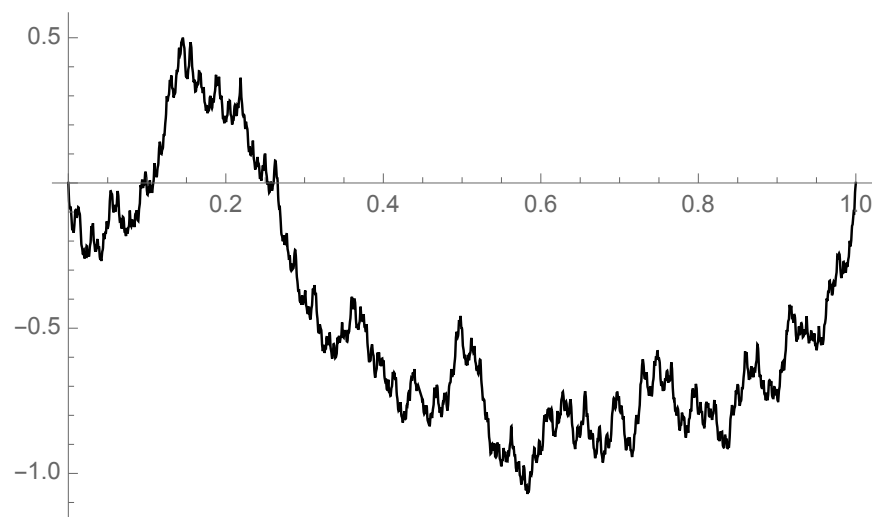


Our class \mathcal{X} has a nonempty intersection with the “Takagi class” introduced by Hata & Yamaguti (1984) and is a subset of the class of generalized Takagi functions studied by Allaart (2009).



Functions in \mathcal{X} for various (deterministic) choices of $\theta_{m,k} \in \{-1, 1\}$

Similarities with sample paths of a Brownian bridge



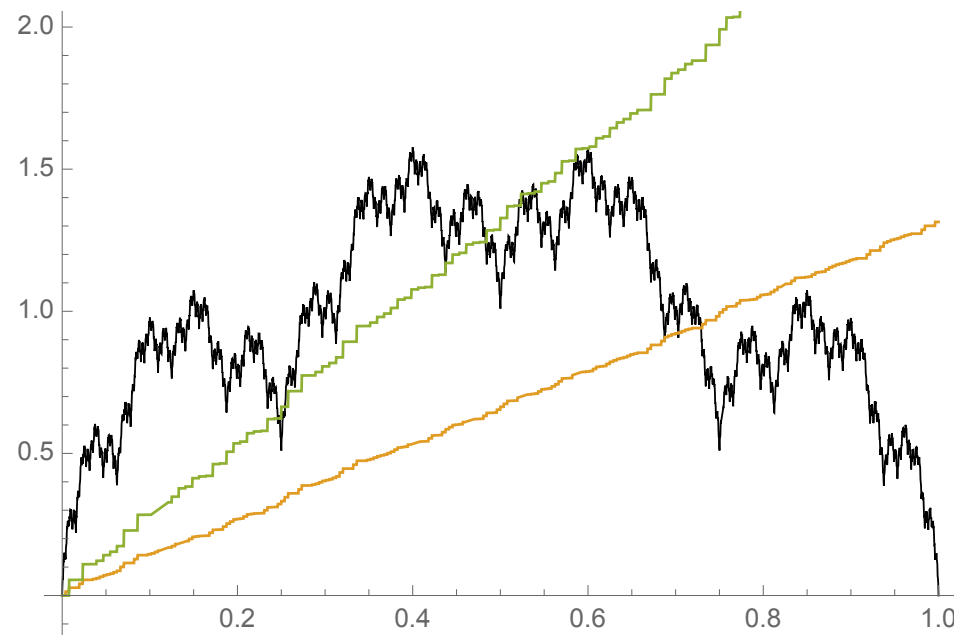
Plots of $x \in \mathcal{X}$ when the $\theta_{m,k}$ form a $\{-1, +1\}$ -valued i.i.d. sequence

- Lévy–Ciesielski construction of the Brownian bridge
- Quadratic variation
- Nowhere differentiability (de Rham 1957, Billingsley 1982, Allaart 2009)
- Hausdorff dimension of the graph of \widehat{x} is $\frac{3}{2}$ (Ledrappier 1992)

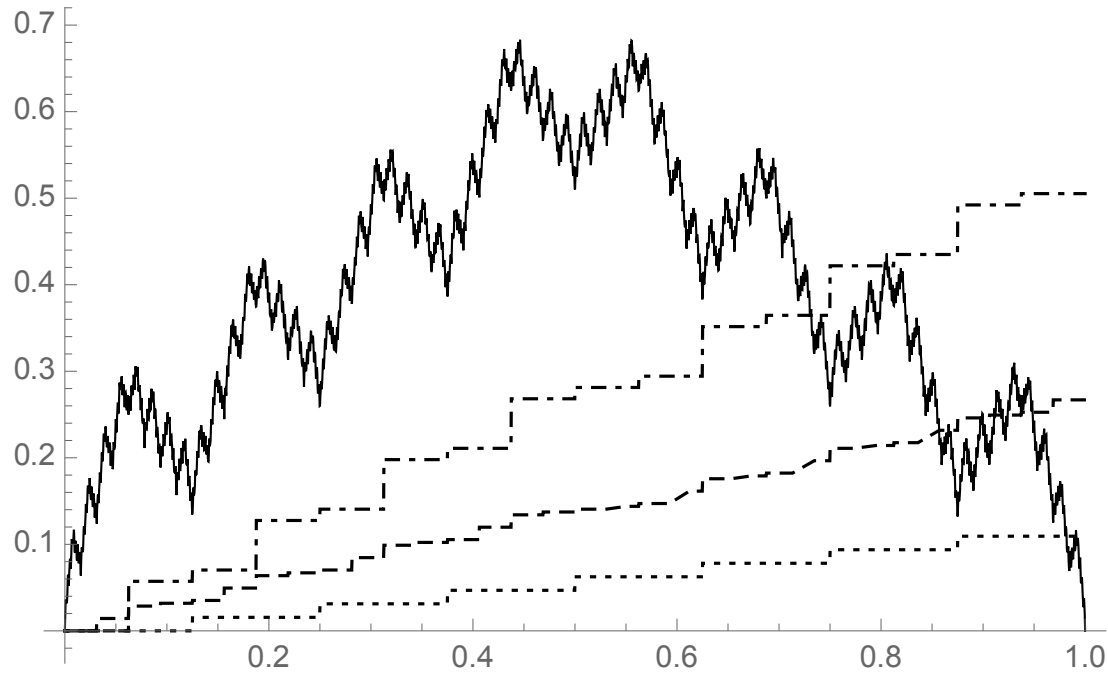
The class of functions with quadratic variation is not a vector space

Proposition 3. Consider the function $y \in \mathcal{X}$ defined through $\theta_{m,k} = (-1)^m$. Then

$$\lim_{n \uparrow \infty} \langle \hat{x} + y \rangle_t^{2n} = \frac{4}{3}t \quad \text{and} \quad \lim_{n \uparrow \infty} \langle \hat{x} + y \rangle_t^{2n+1} = \frac{8}{3}t$$



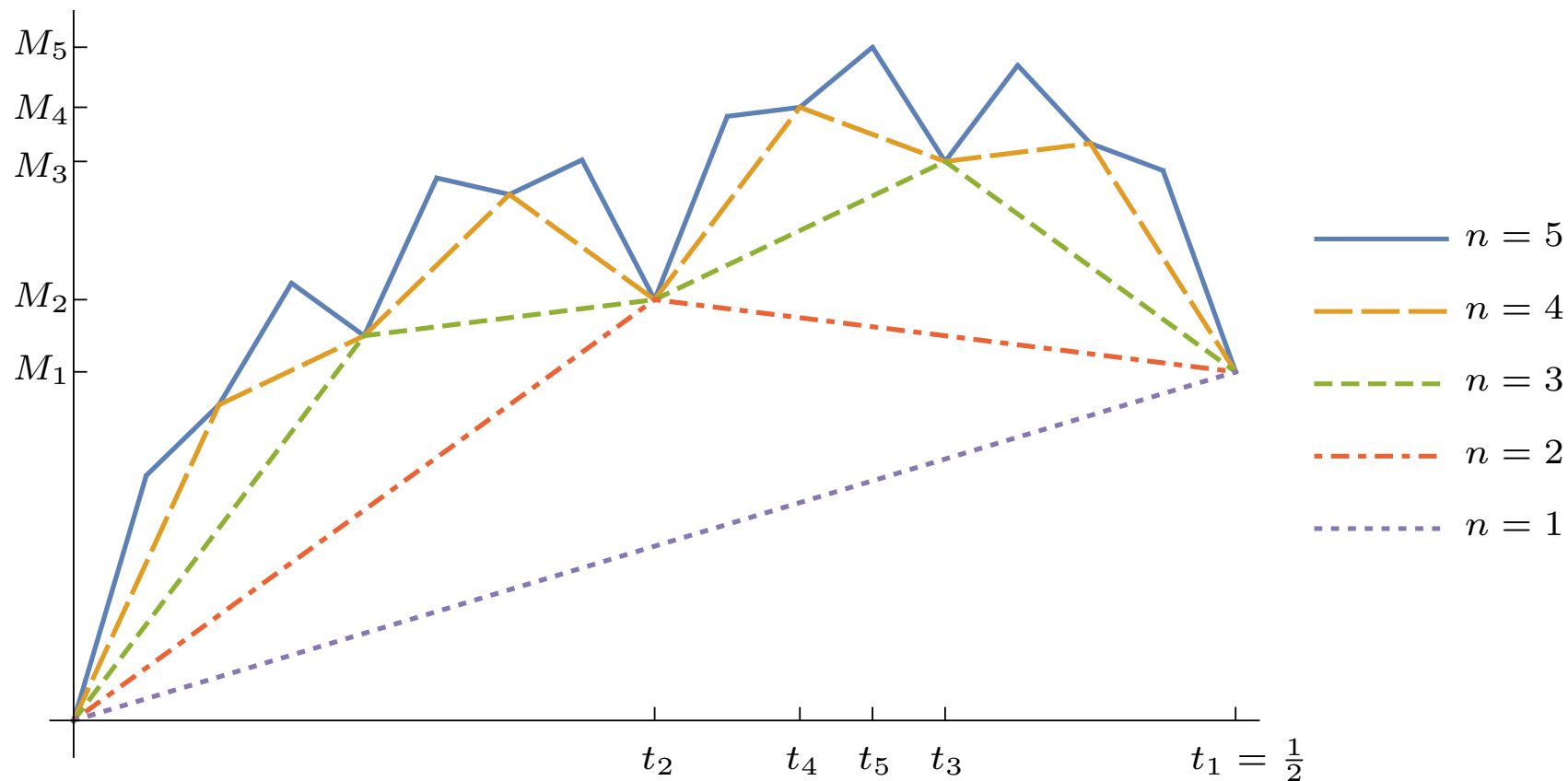
The function $\hat{x} + y$ with $\langle \hat{x} + y \rangle^7$ and $\langle \hat{x} + y \rangle^8$



A function $z \notin \mathcal{X}$ with exactly three distinct accumulation points for $\langle z \rangle_t^n$

The maximum of \hat{x}

Kahane (1959) showed that the maximum of the Takagi function is $\frac{3}{2}$. For \hat{x} , we need different arguments.



Functions $\hat{x}^n(t) := \sum_{m=0}^{n-1} \sum_{k=0}^{2^m-1} e_{m,k}(t)$ and their maxima on $[0, \frac{1}{2}]$

The preceding plot suggests the recursions

$$t_{n+1} = \frac{t_n + t_{n-1}}{2} \quad \text{and} \quad M_{n+1} = \frac{M_n + M_{n-1}}{2} + 2^{-\frac{n+2}{2}}$$

These are solved by

$$t_n = \frac{1}{3}(1 - (-1)^n 2^{-n}) \quad \text{and} \quad M_n = \frac{1}{3} \left(2 + \sqrt{2} + (-1)^{n+1} 2^{-n} (\sqrt{2} - 1) \right) - 2^{-n/2}$$

By sending $n \uparrow \infty$, we obtain:

Theorem 1. *The uniform maximum of functions in \mathcal{X} is attained by \hat{x} and given by*

$$\max_{x \in \mathcal{X}} \max_{t \in [0,1]} |x(t)| = \max_{t \in [0,1]} \hat{x}(t) = \frac{1}{3}(2 + \sqrt{2}).$$

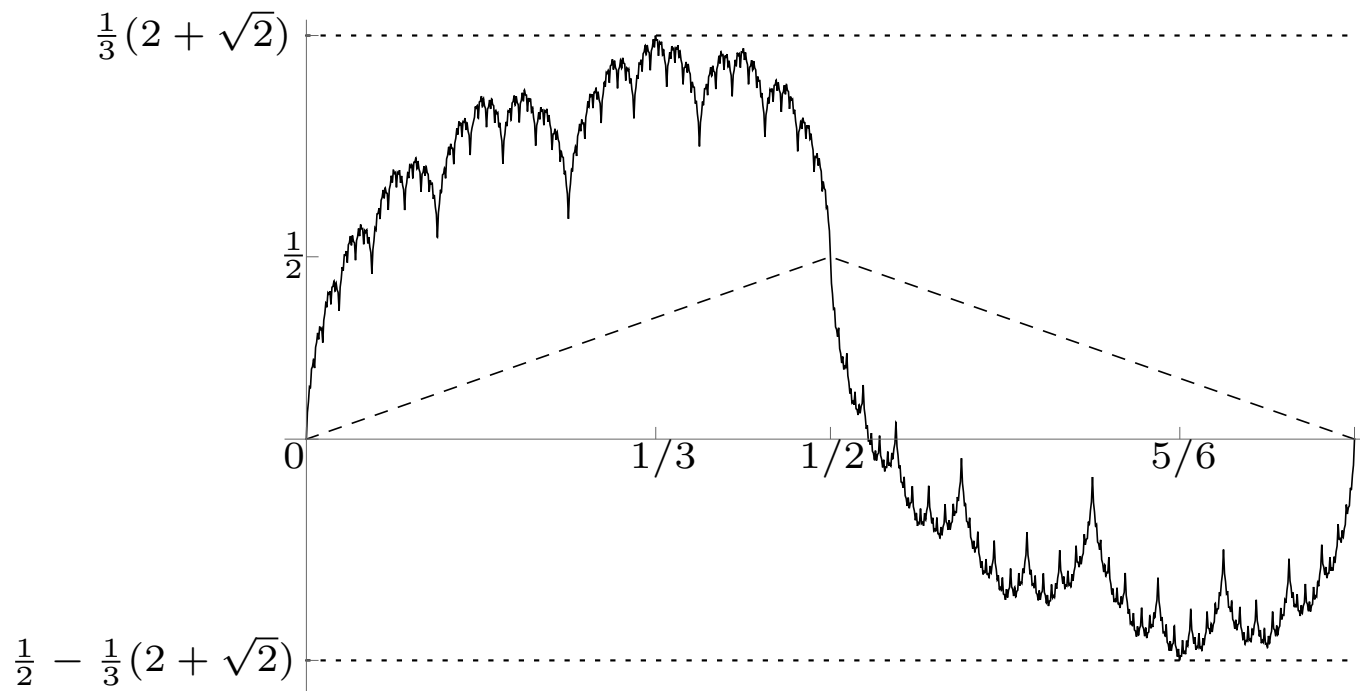
Maximal points are $t = \frac{1}{3}$ and $t = \frac{2}{3}$.

Corollary 1. *The maximal **uniform** oscillation of functions in \mathcal{X} is*

$$\max_{x \in \mathcal{X}} \max_{s, t \in [0, 1]} |x(t) - x(s)| = \frac{1}{6}(5 + 4\sqrt{2})$$

where the respective maxima are attained at $s = 1/3$, $t = 5/6$, and

$$x^* := e_{0,0} + \sum_{m=1}^{\infty} \left(\sum_{k=0}^{2^{m-1}-1} e_{m,k} - \sum_{\ell=2^{m-1}}^{2^m-1} e_{m,\ell} \right)$$



Uniform moduli of continuity

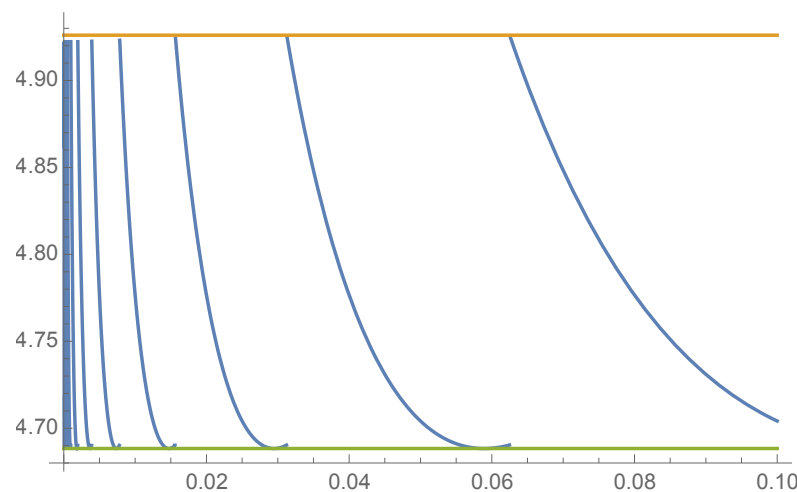
Kahane (1959), Kôno (1987), Hata & Yamaguti (1984), and Allaart (2009) studied moduli of continuity for (generalized) Takagi functions. However, their arguments are not applicable to the functions in \mathcal{X} .

Let

$$\omega(h) := \left(1 + \frac{1}{\sqrt{2}}\right) h 2^{\lfloor -\log_2 h \rfloor / 2} + \frac{1}{3}(\sqrt{8} + 2) 2^{-\lfloor -\log_2 h \rfloor / 2}$$

Then $\omega(h) = O(\sqrt{h})$ as $h \downarrow 0$. More precisely,

$$\liminf_{h \downarrow 0} \frac{\omega(h)}{\sqrt{h}} = 2\sqrt{\frac{4}{3} + \sqrt{2}} \qquad \limsup_{h \downarrow 0} \frac{\omega(h)}{\sqrt{h}} = \frac{1}{6}(11 + 7\sqrt{2})$$



Theorem 2 (Moduli of continuity).

(a) The function \widehat{x} has ω as its modulus of continuity. More precisely,

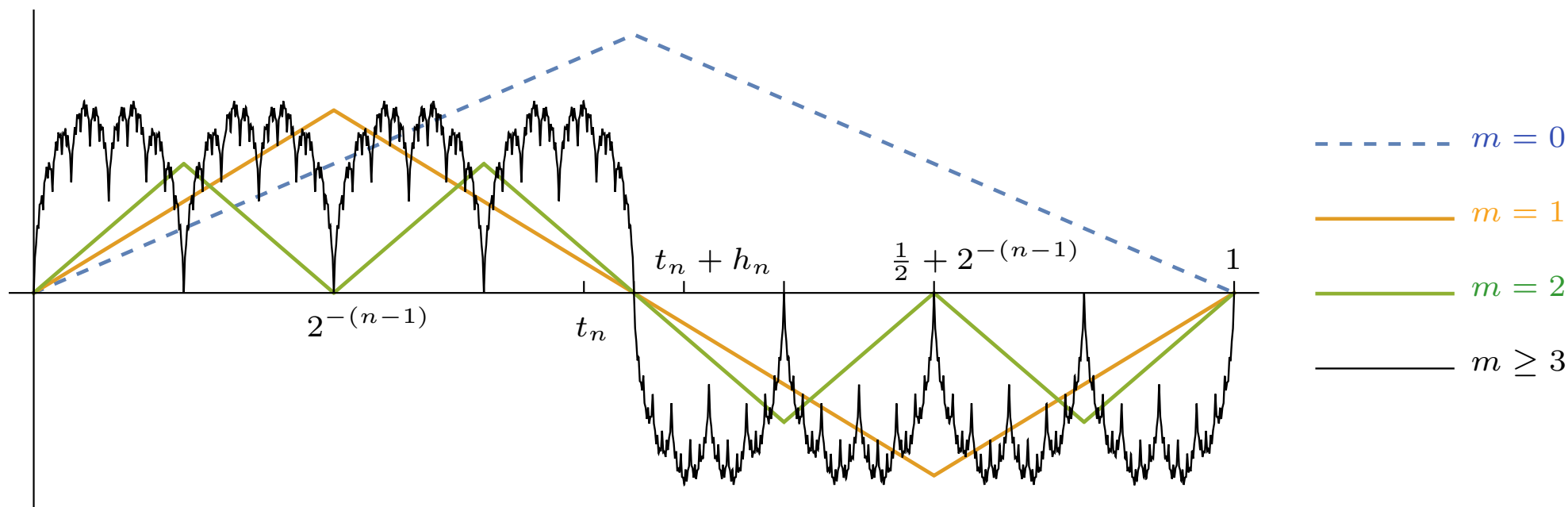
$$\limsup_{h \downarrow 0} \max_{0 \leq t \leq 1-h} \frac{|\widehat{x}(t+h) - \widehat{x}(t)|}{\omega(h)} = 1$$

(b) An exact *uniform* modulus of continuity for functions in \mathcal{X} is given by $\sqrt{2}\omega$. That is,

$$\limsup_{h \downarrow 0} \sup_{x \in \mathcal{X}} \max_{0 \leq t \leq 1-h} \frac{|x(t+h) - x(t)|}{\omega(h)} = \sqrt{2}$$

Moreover, the above supremum over functions $x \in \mathcal{X}$ is attained by the function x^* in the sense that

$$\limsup_{h \downarrow 0} \max_{0 \leq t \leq 1-h} \frac{|x^*(t+h) - x^*(t)|}{\omega(h)} = \sqrt{2}$$



The Faber–Schauder development of x^* is plotted individually for generations $m \leq n - 1$ (with $n = 3$ here).

The aggregated development over all generations $m \geq n$ corresponds to a sequence of rescaled functions \hat{x} .

$$\omega(h) = \underbrace{\left(1 + \frac{1}{\sqrt{2}}\right)h2^{\lfloor -\log_2 h \rfloor / 2}}_{\text{linear part}} + \underbrace{\frac{1}{3}(\sqrt{8} + 2)2^{-\lfloor -\log_2 h \rfloor / 2}}_{\text{self-similar part}}$$

Consequences

- Functions in \mathcal{X} are uniformly Hölder continuous with exponent $\frac{1}{2}$
- Functions in \mathcal{X} have a finite 2-variation and hence can serve as integrators in rough path theory
- \mathcal{X} is a compact subset of $C[0, 1]$

Thank you

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