



# SCCER-FURIES

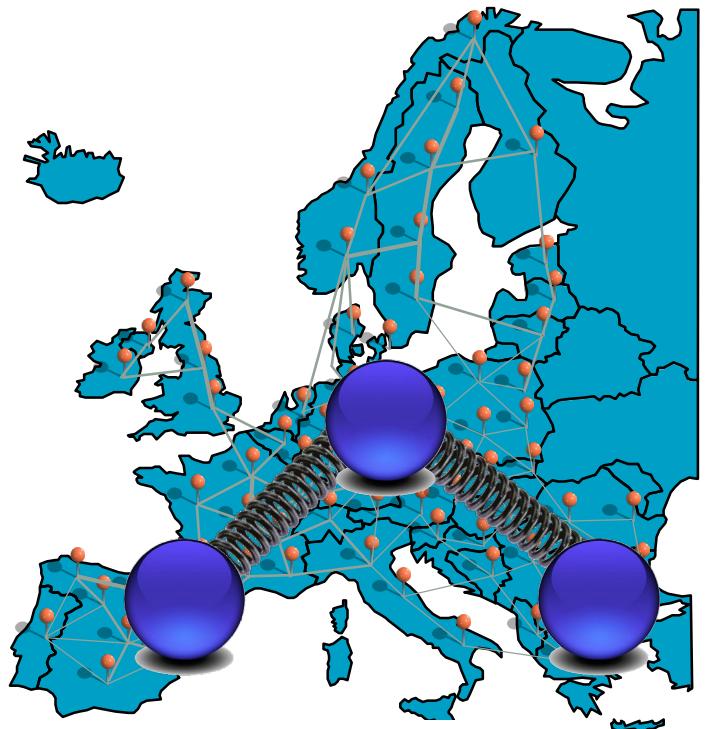
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Dr. Dobrowolski Jean, ZHAW

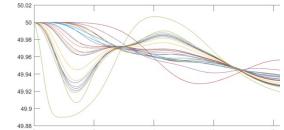
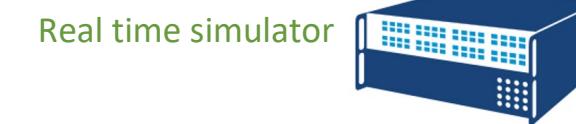
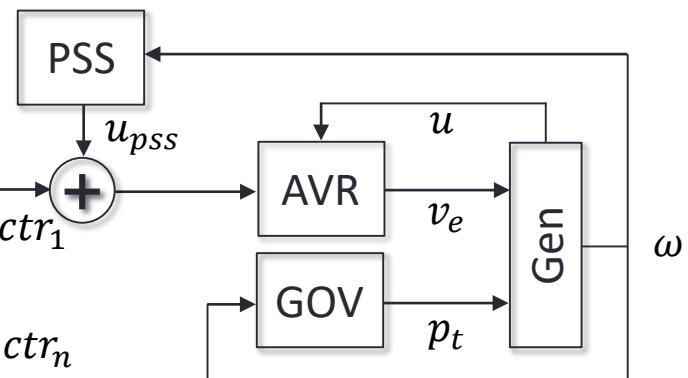
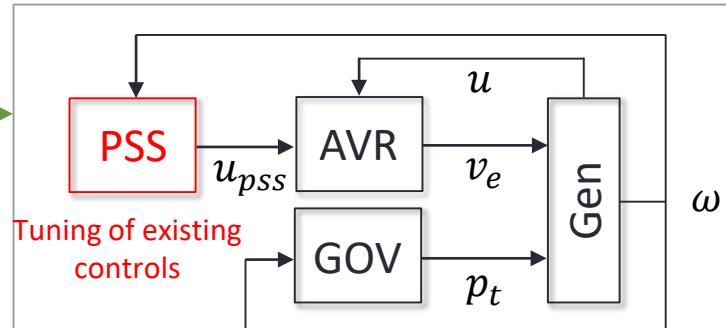
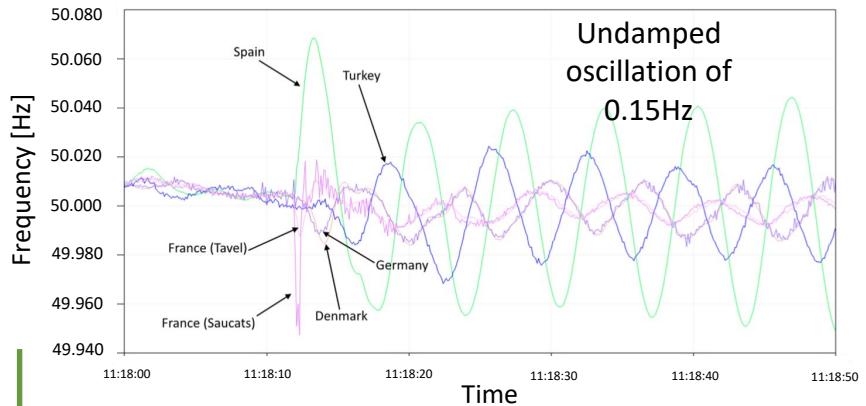
**SCCER-FURIES Annual Meeting, October 28<sup>th</sup> 2020**

***Dynamic Transmission System Emulator for  
Stability Assessment***

For more information : [xdow@zhaw.ch](mailto:xdow@zhaw.ch)



Control solutions to improve stability



Simulations

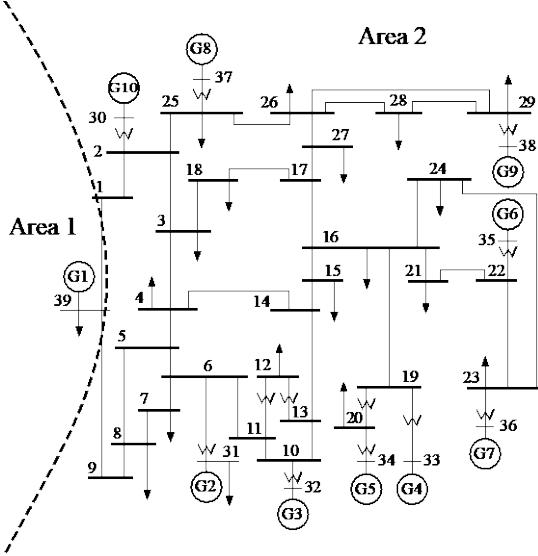
Test solutions





### European model (entso-e):

- 6147 generators
- 23253 buses
- 7377 loads
- 3-4 areas



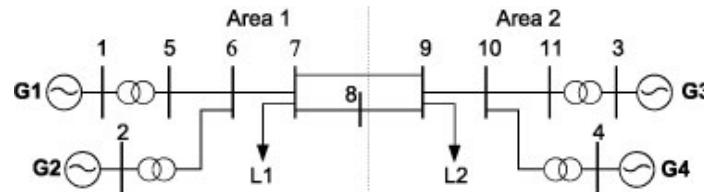
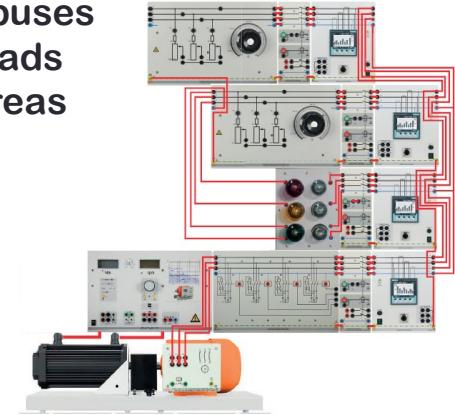
### New England model:

- 10 generators
- 39 buses
- 19 loads
- 2 areas

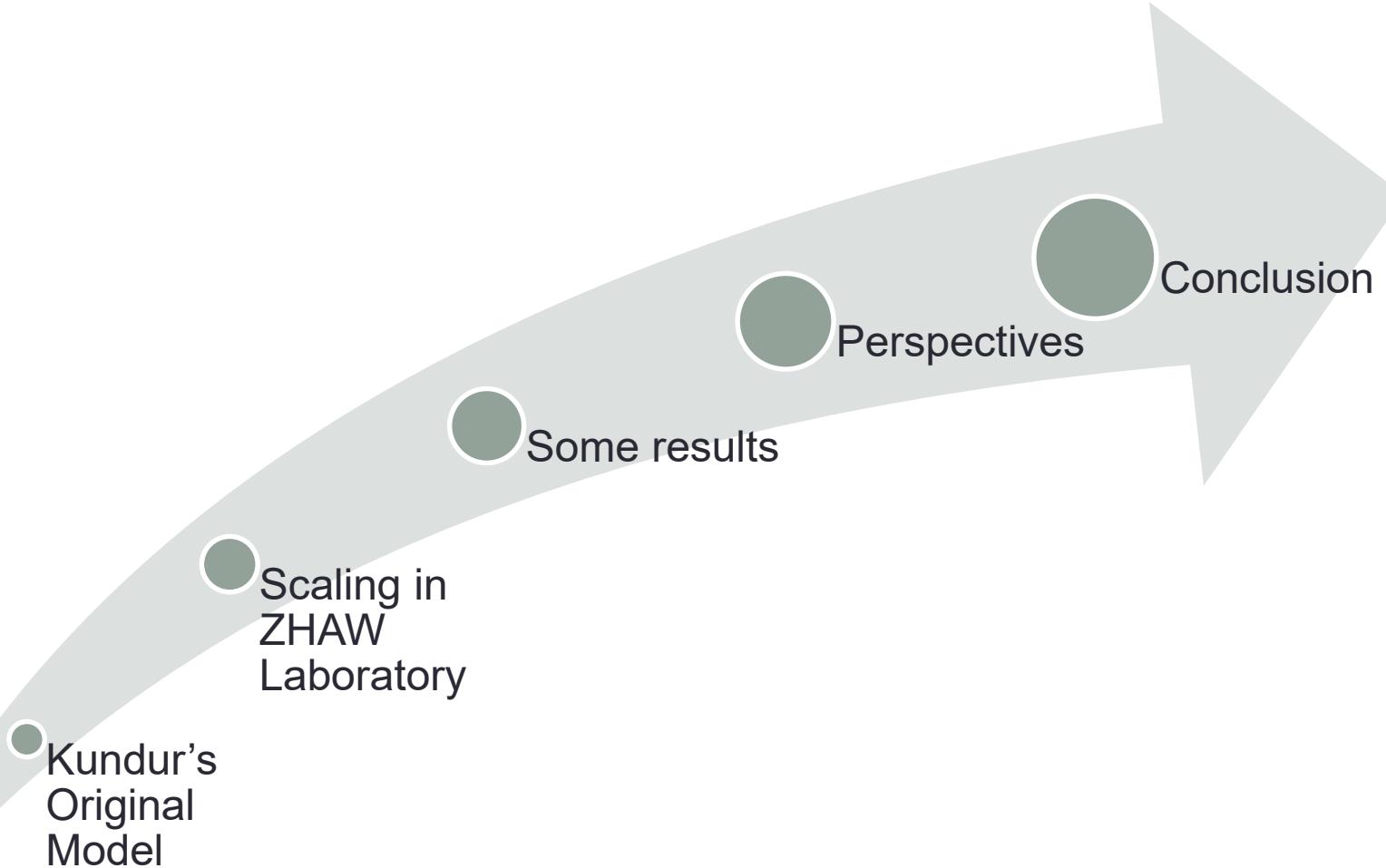
DIGITAL  
SILENT

### Kundur two-areas model:

- 4 generators
- 11 buses
- 2 loads
- 2 areas

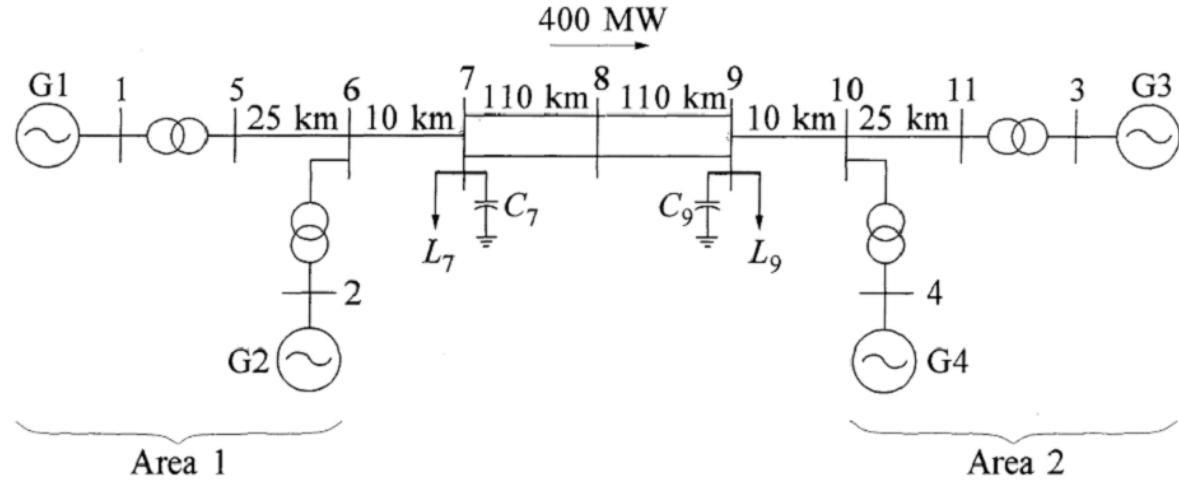


# Outline



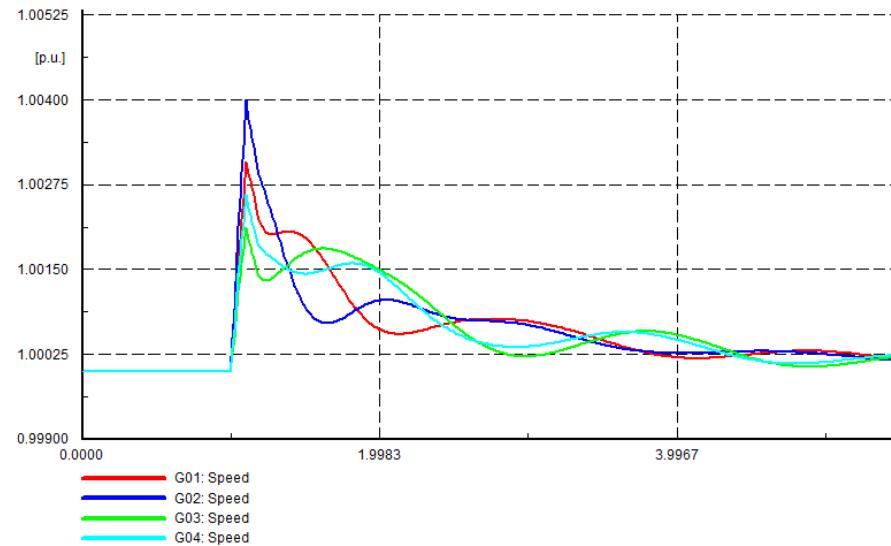


# Kundur's original model



**The smallest representation of a transmission grid**

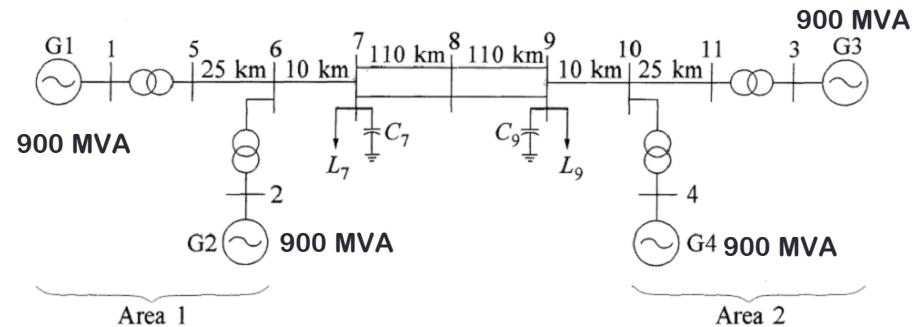
- 4 generators
- 11 buses
- 2 loads
- 2 areas



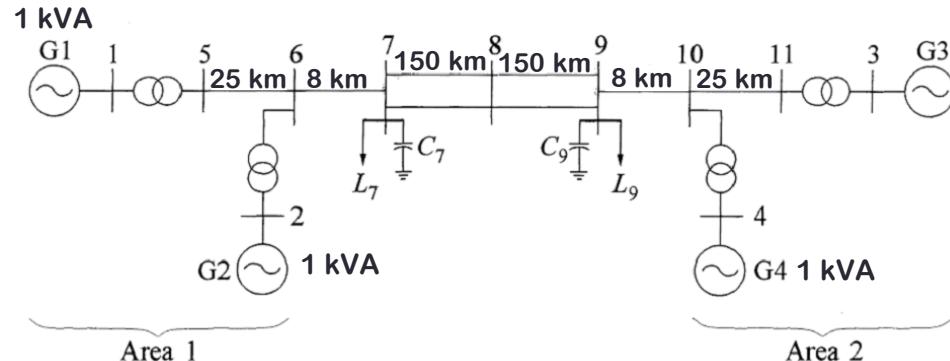
	Name	Real part 1/s	Imaginary part rad/s	Magnitude 1/s	Angle deg	Damped Frequency Hz	Period s	Damping 1/s	Damping Ratio
#	Mode 00001	-2.050181	6.834751	7.135619	106.697369	1.087784432	0.919299	2.050181	0.2873163
#	Mode 00002	-2.132377	6.116780	6.477810	109.219124	0.973515794	1.027204	2.132377	0.3291686
#	Mode 00003	-0.469408	3.224757	3.258742	98.282031	0.513236022	1.948421	0.469408	0.1440458
#	Mode 00004	-8.427680	3.262835	9.037249	158.835739	0.519296371	1.925682	8.427680	0.9325491
#	Mode 00005	-1.443360	-0.000000	1.443360	-180.	0.	0.	1.443360	1.
#	Mode 00006	-0.048227	0.000000	0.048227	180.	0.	0.	0.048227	1.
#	Mode 00007	-0.715944	0.	0.715944	180.	0.	0.	0.715944	1.
#	Mode 00008	-0.501082	0.029956	0.501977	176.578730	0.004767722	209.743747	0.501082	0.9982177
#	Mode 00009	-0.501082	-0.029956	0.501977	-176.578730	0.004767722	209.743747	0.501082	0.9982177
#	Mode 00010	-0.346709	0.	0.346709	-180.	0.	0.	0.346709	1.
#	Mode 00011	-2.586386	0.233491	2.596904	174.841480	0.037161365	26.909669	2.586386	0.9959497
#	Mode 00012	-3.897253	0.471892	3.925719	173.096046	0.075104004	13.314869	3.897253	0.9927496
#	Mode 00013	-3.075658	0.000000	3.075658	180.	0.000000000	0.	3.075658	1.
#	Mode 00014	-2.586386	-0.233491	2.596904	-174.841480	0.037161365	26.909669	2.586386	0.9959497
#	Mode 00015	-4.114402	-0.000000	4.114402	-180.	0.000000000	0.	4.114402	1.
#	Mode 00016	-4.768618	0.000000	4.768618	180.	0.000000000	0.	4.768618	1.
#	Mode 00017	-0.100265	0.000000	0.100265	179.999999	0.000000000	0.	0.100265	1.



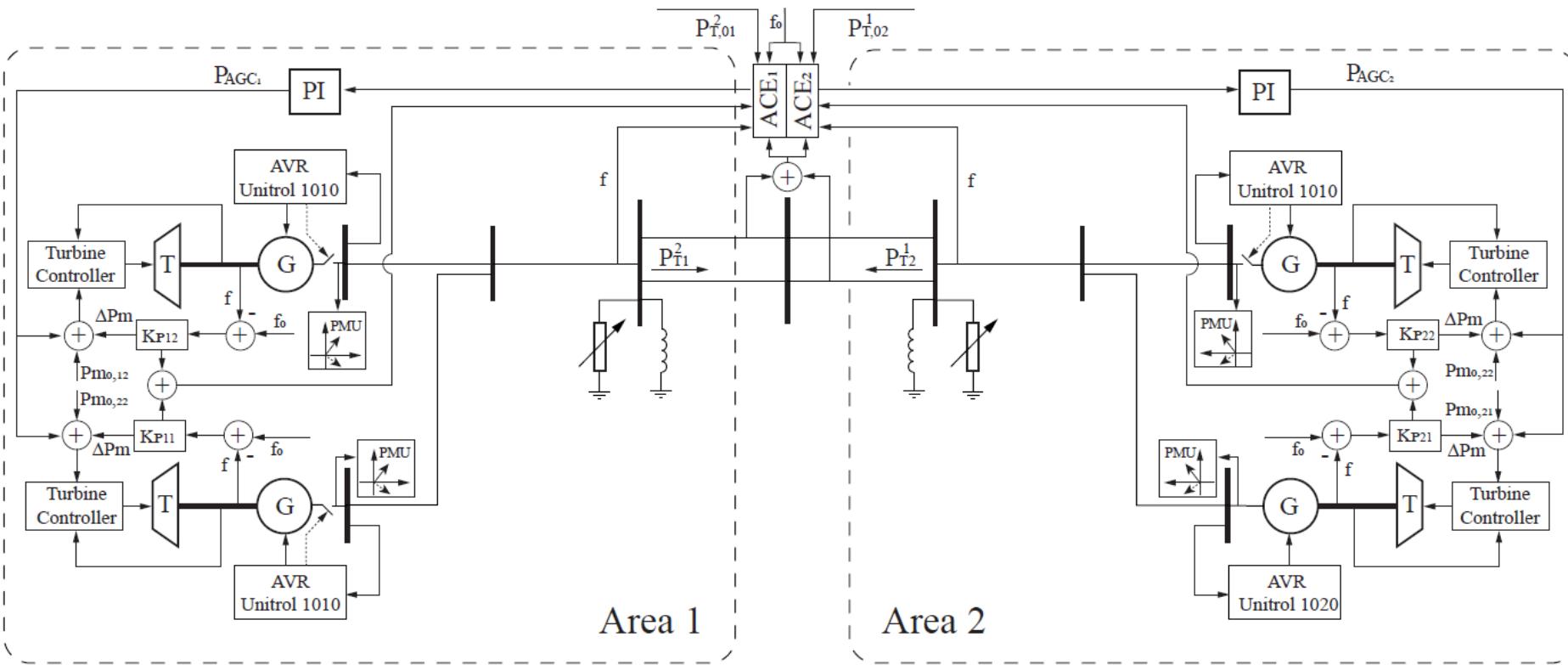
## ZHAW laboratory

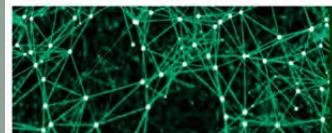


Original model

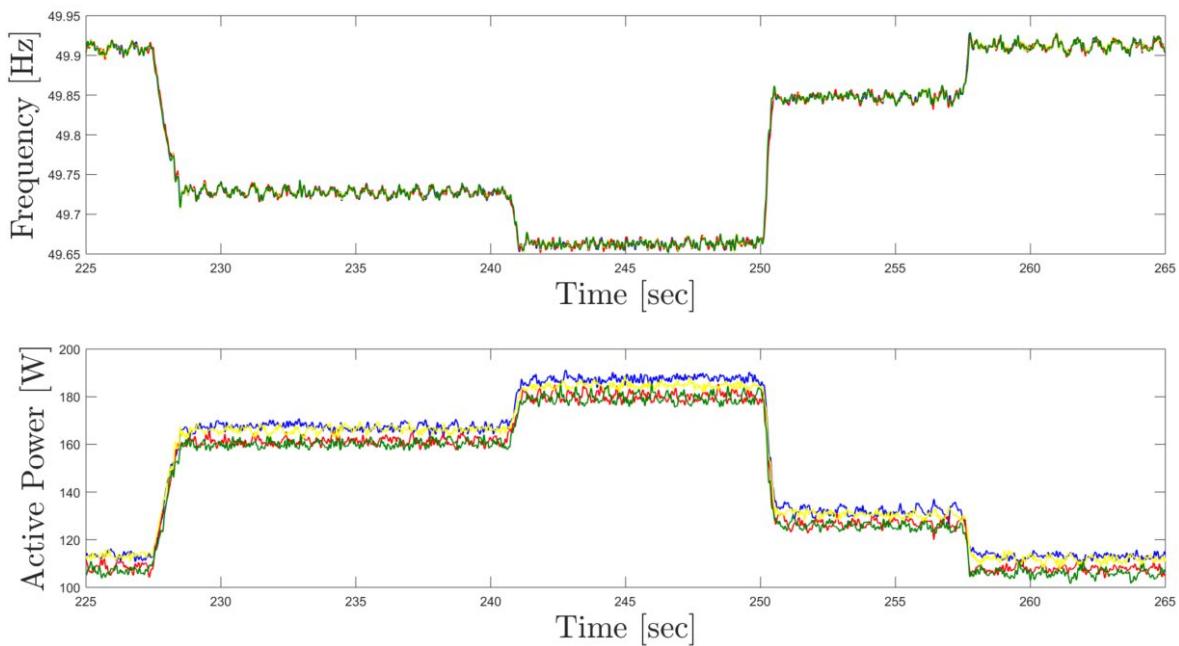


# Final implementation

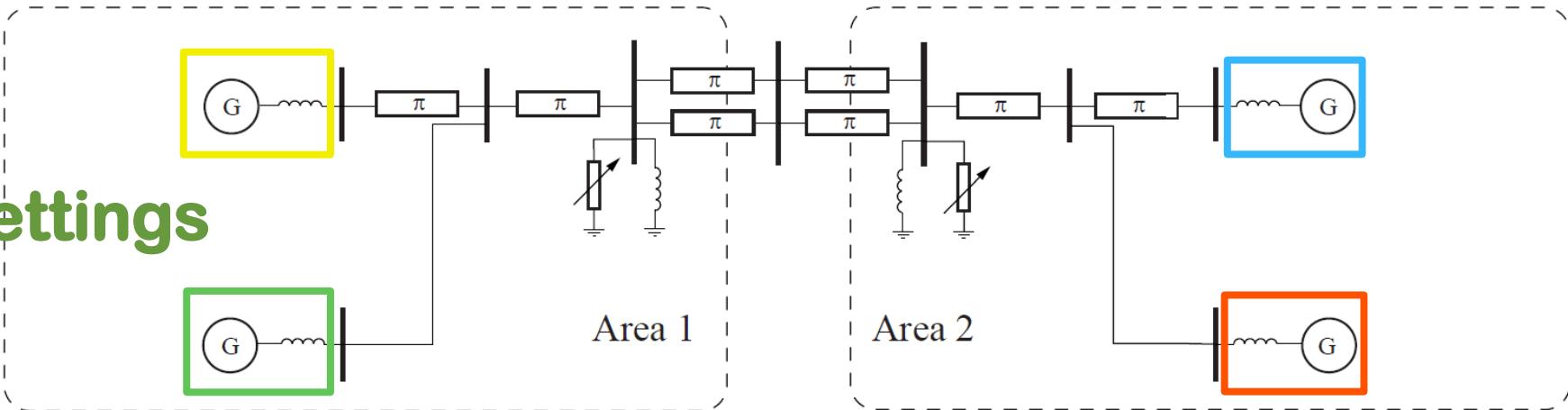




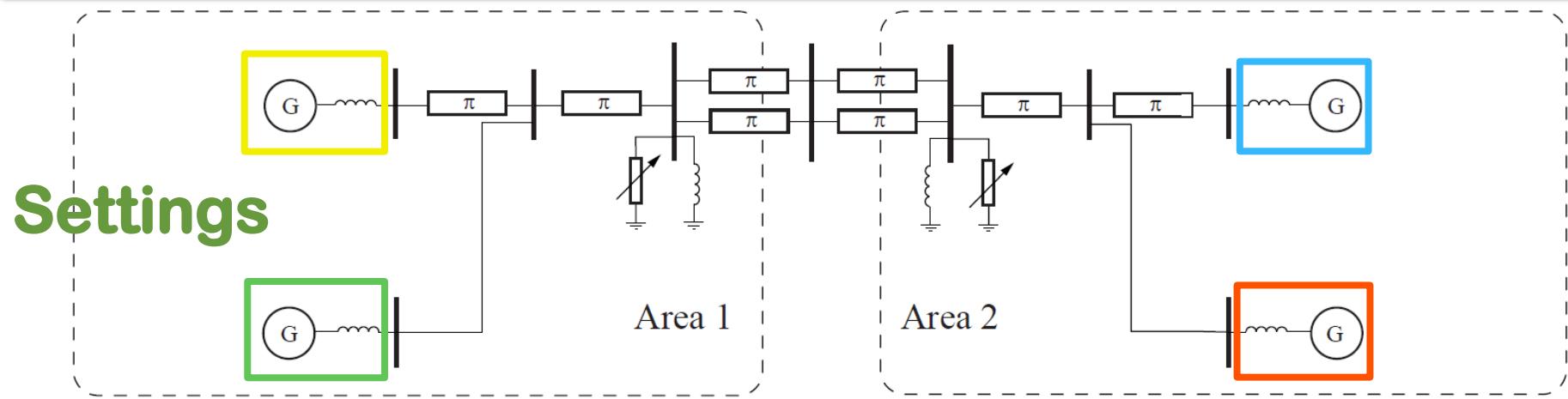
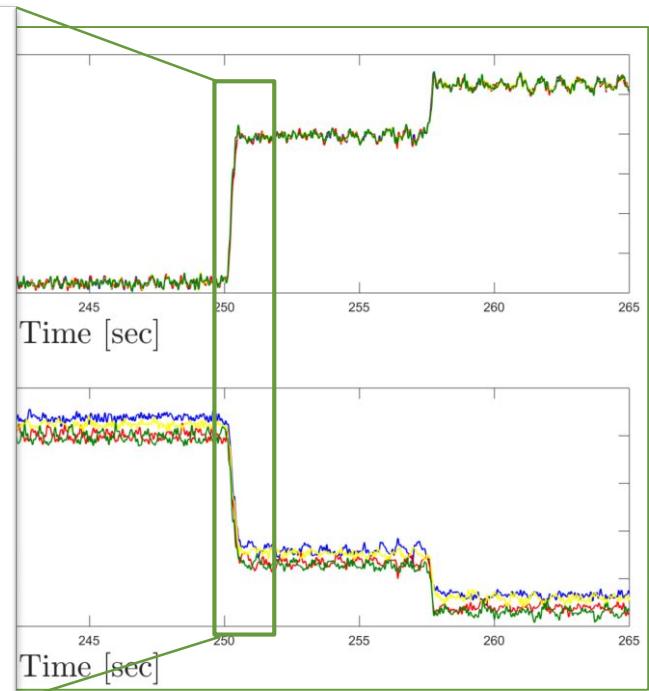
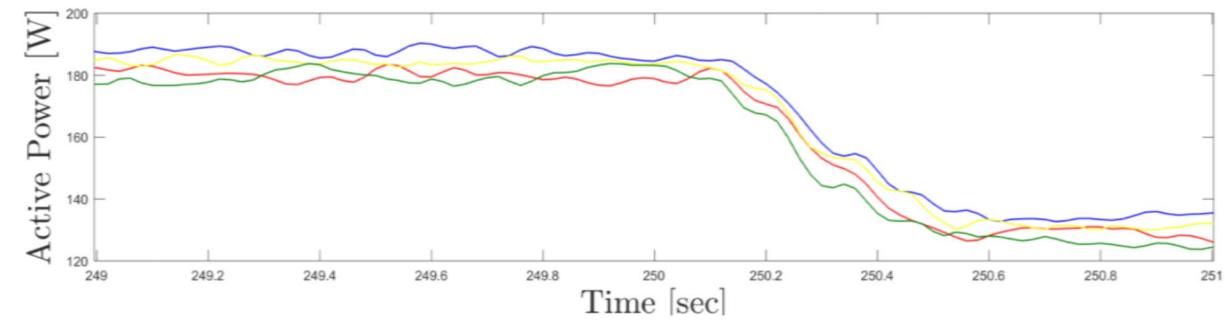
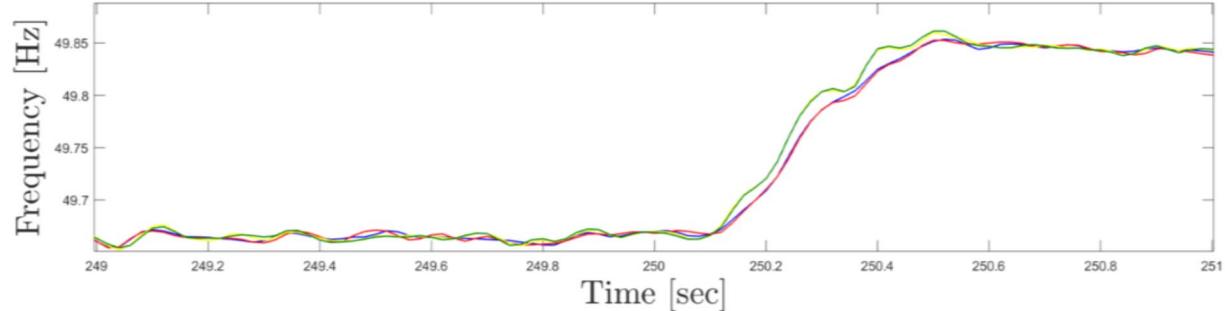
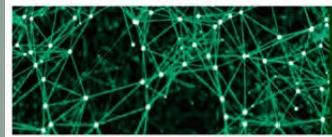
## Without inertia

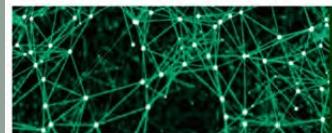


**zhaw** Laboratory view



## Settings





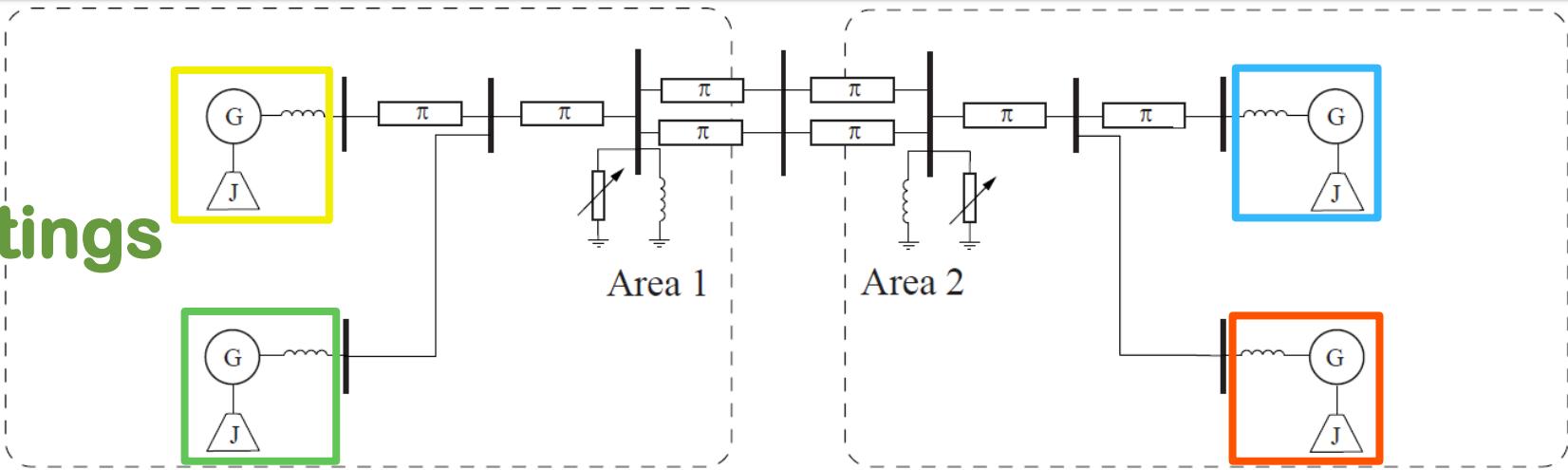
## Effect of inertia

**zhaw** Laboratory view

Frequency [Hz]

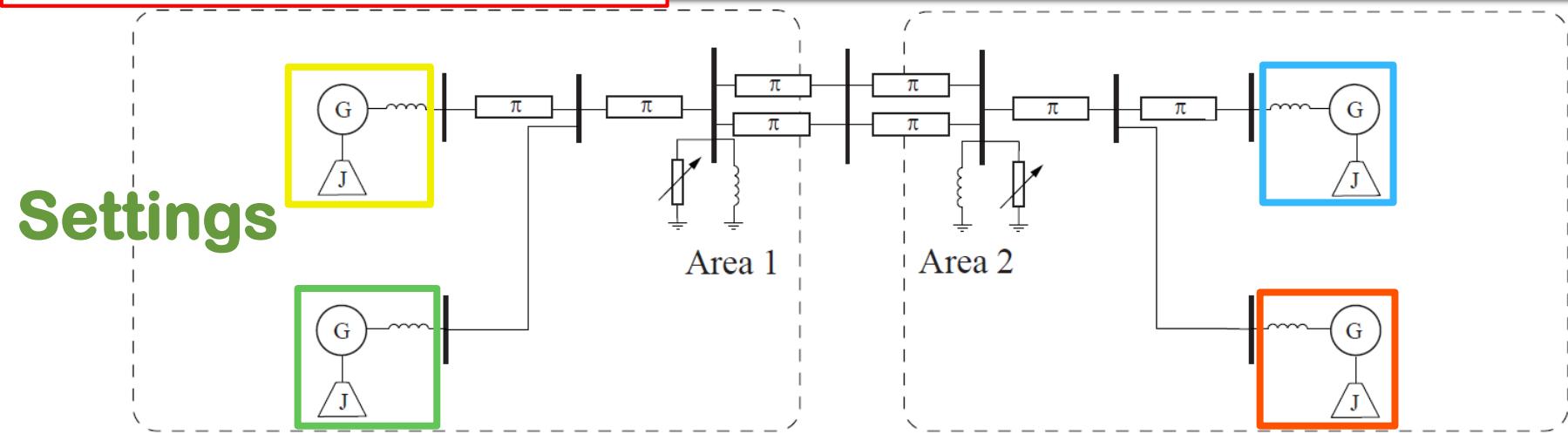
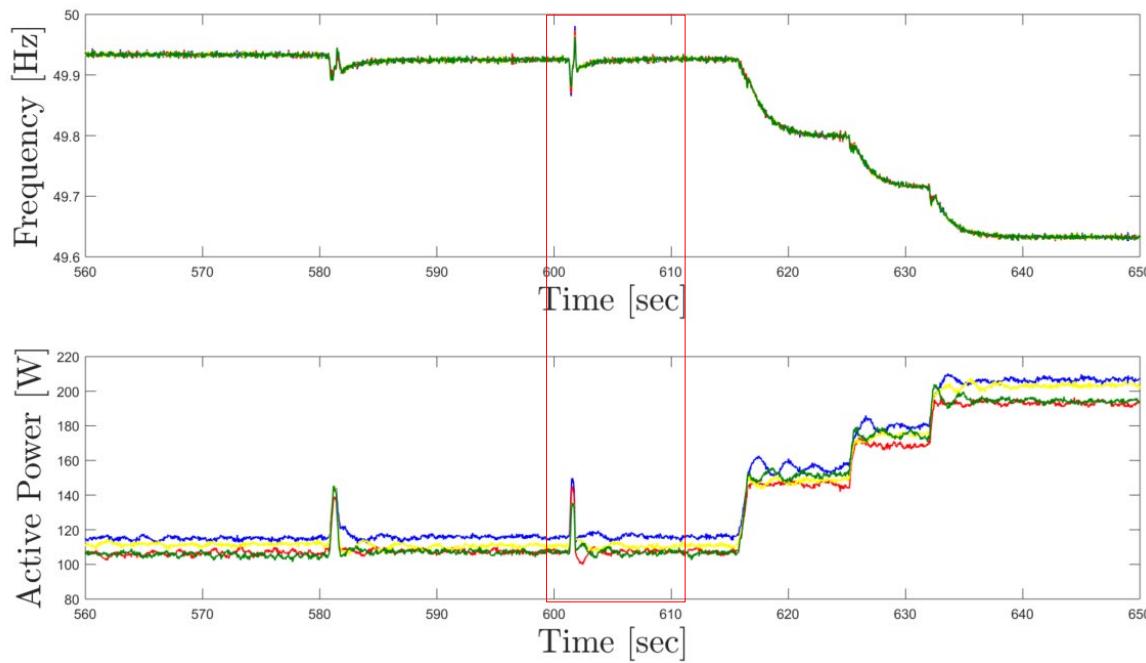
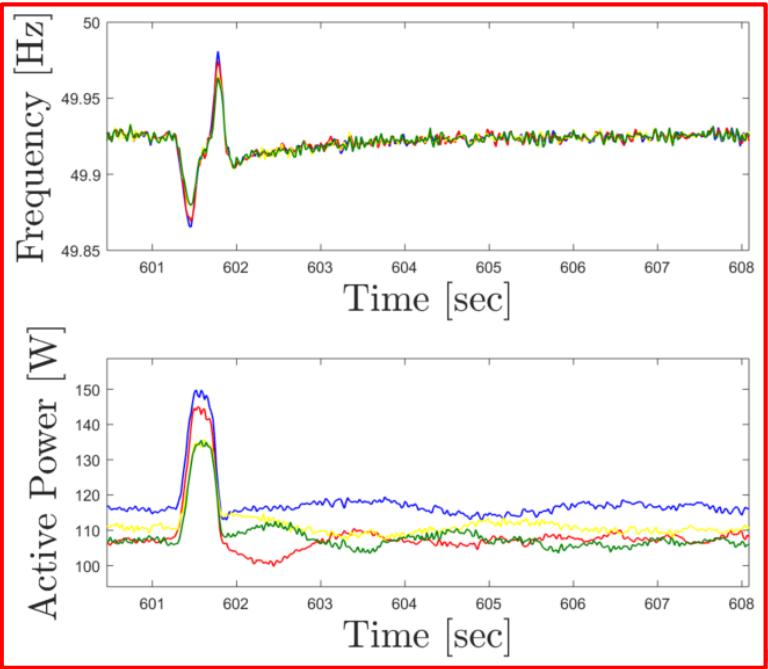
Active Power [W]

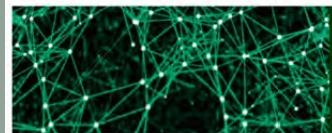
Settings





## Effect of inertia



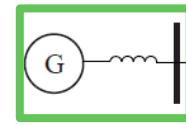
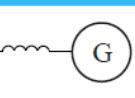
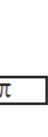
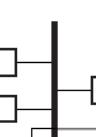
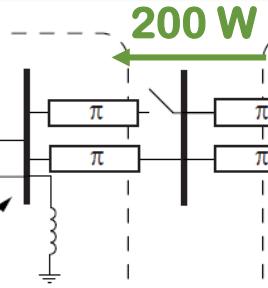
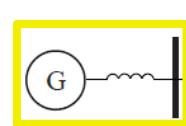


## Trip of a line

**zhaw** Laboratory view

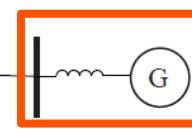
Frequency [Hz]

Active Power [W]

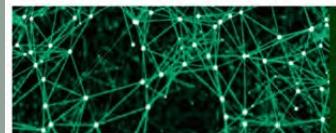


Area 1

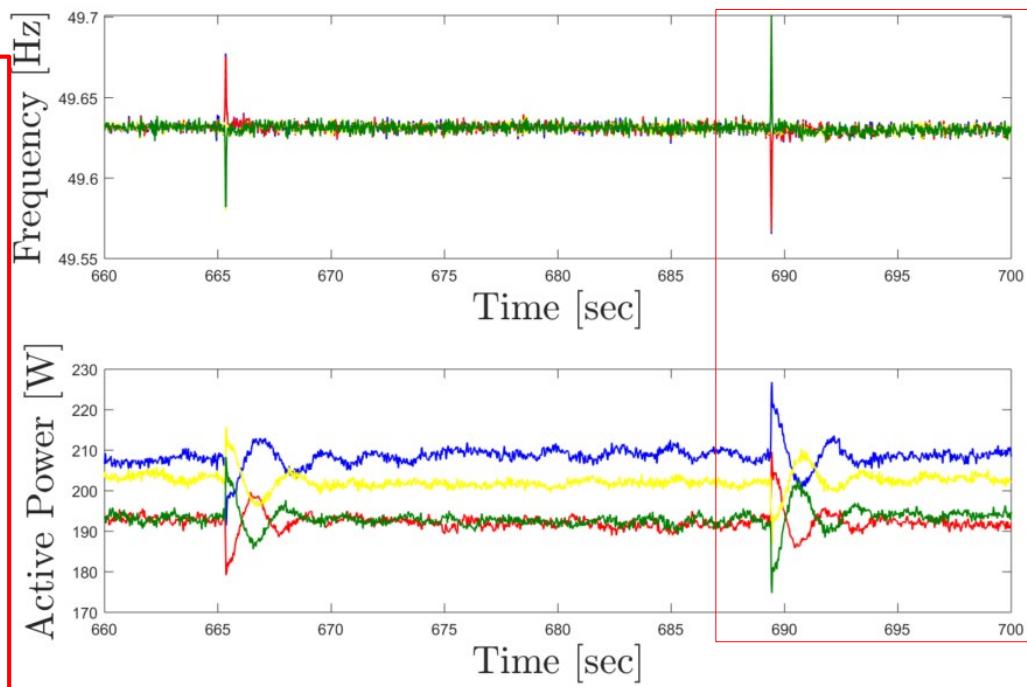
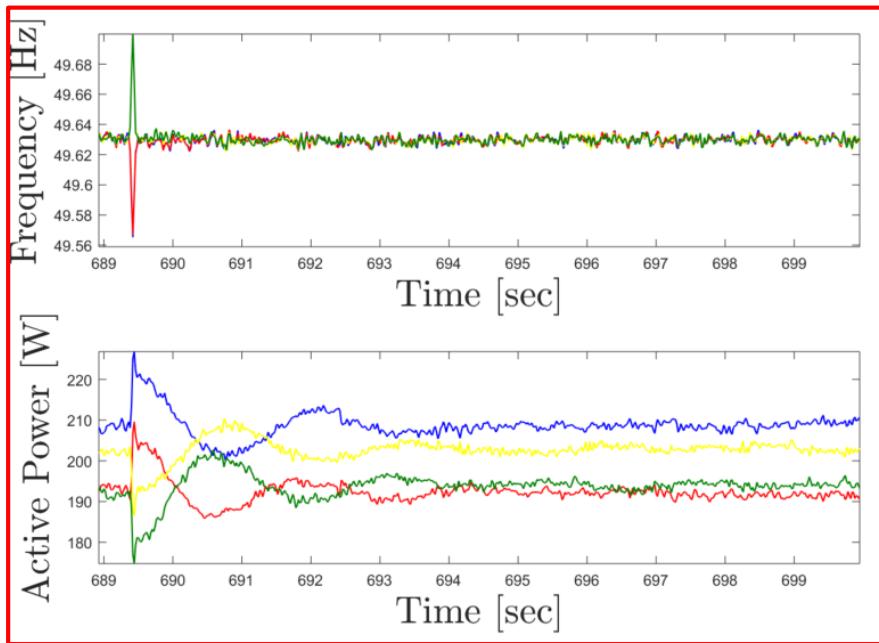
Area 2



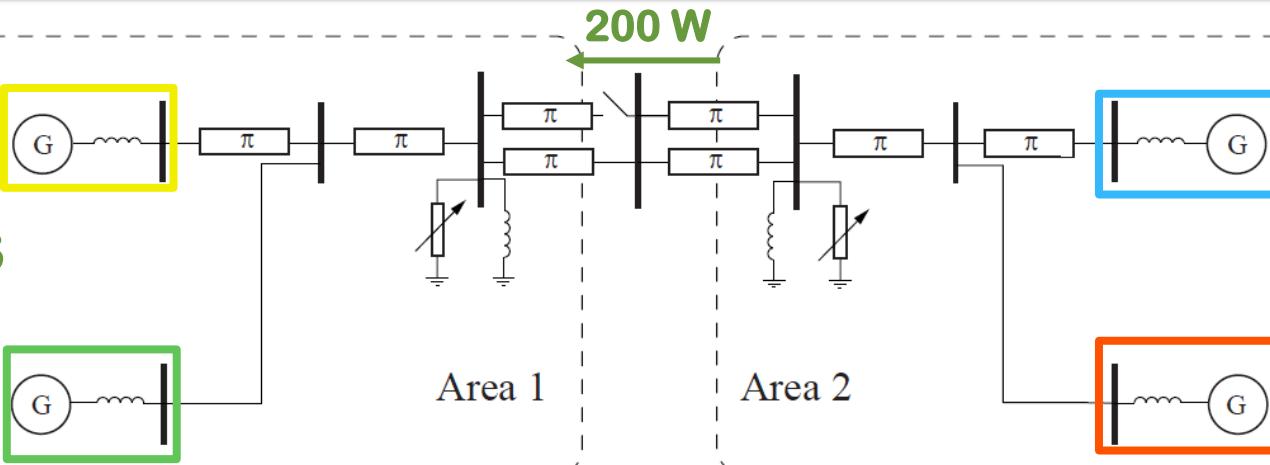
Settings

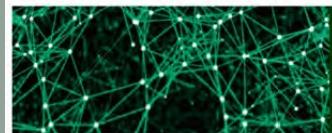


## Trip of a line

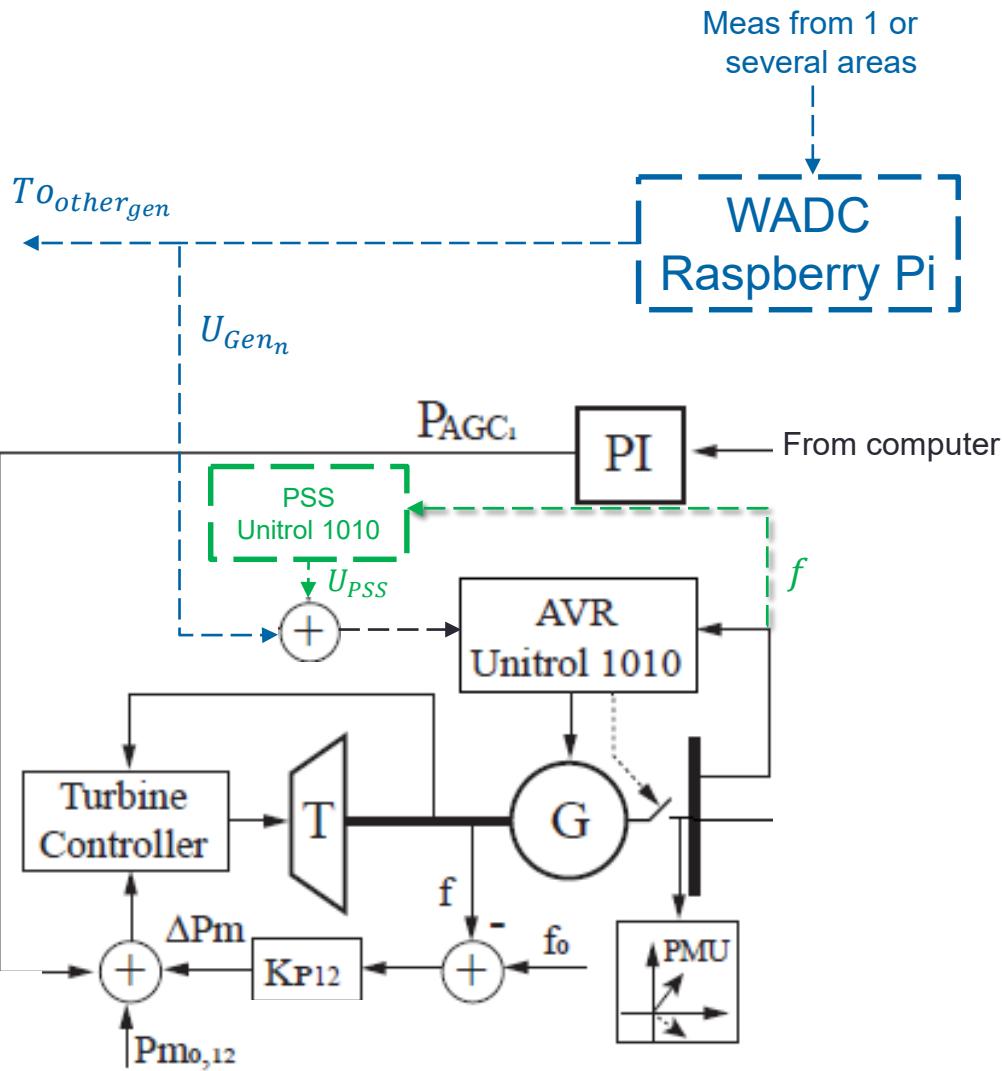
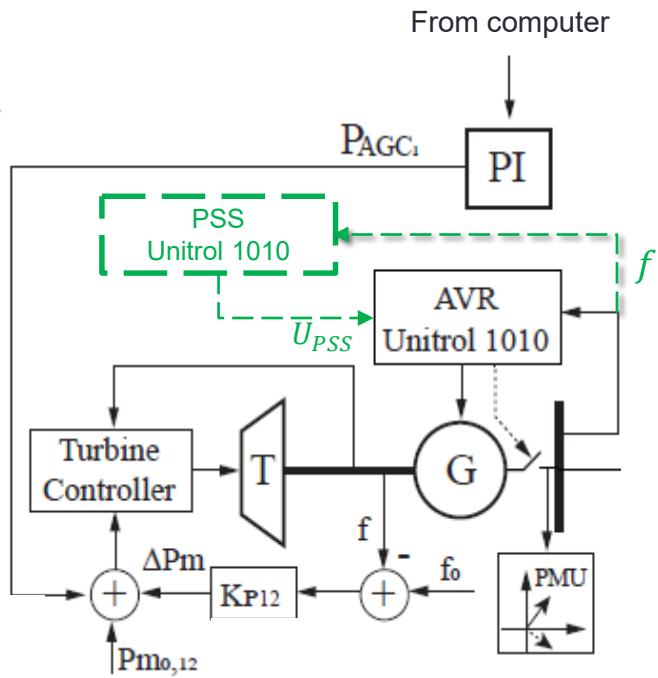


## Settings

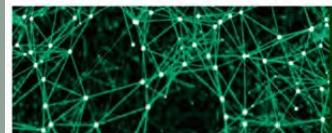




## PSS implementation



## WADC implementation



# Conclusion



- Implementation of Kundur's transmission grid model using Lucas Nüelle systems
- Possibility to change inertia, to trip lines, to trip generators, to activate / deactivate secondary controllers...
- Ability to represent inter-area oscillations as well as local oscillations
- Possibility to test some controllers already designed in simulation:
  - WADC approaches: "Centralized Wide Area Damping Controller for Power System Oscillation Problems" 2019 IEEE Milan PowerTech.
  - New PSS tuning: "Inter-area oscillation control based on eigensystem realization approach." 2018 IEEE International Autumn Meeting on Power, Electronics and Computing (ROPEC).
  - Feedback control: "State-feedback control for damping inter-area oscillations on electrical power systems." 2018 IEEE Autumn Meeting on Power, Electronics and Computing (ROPEC 2018)

