# Semidefinite programming hierarchies for packing and energy minimization (4/4) 

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## Topics for the four talks

1. Sums-of-squares hierarchies for polynomial optimization
2. Moment hierarchies for polynomial optimization
3. Packing problems
4. Energy minimization problems

## Question 1

How can we use the Lasserre hierarchy for $0 / 1$ polynomial optimization problems to derive a hierarchy for energy minimization on $S^{n-1}$ ?

## Energy minimization on $S^{n-1}$

Find the minimum of

$$
\sum_{1 \leq i<j \leq N} \frac{1}{\left\|p_{i}-p_{j}\right\|}
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over all sets $\left\{p_{1}, \ldots, p_{N}\right\}$ of $N$ distinct points on $S^{n-1}$

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For $n=3$ this is the Thomson problem

## Energy minimization on $\{1, \ldots, n\}$

Given a symmetric matrix $W \in \mathbb{R}^{n \times n}$, find the minimum of

$$
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As a $0 / 1$ polynomial optimization problem:

$$
\min \left\{\sum_{1 \leq i<j \leq N} W_{i, j} x_{i} x_{j}: x \in\{0,1\}^{n}, \sum_{i=1}^{n} x_{i}=N\right\}
$$

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Localizing matrices:

$$
M_{t}^{q}(y)_{J, J^{\prime}}= \begin{cases}\sum_{S} q_{S} y_{J \cup J^{\prime} \cup S} & \text { if }\left|J \cup J^{\prime}\right| \leq 2 t-\operatorname{deg}(q), \\ \text { unspecified } & \text { otherwise }\end{cases}
$$

for $|J|,\left|J^{\prime}\right| \leq t$

## Energy minimization on $\{1, \ldots, n\}$

Formulation as a $0 / 1$ polynomial optimization problem:

$$
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This reduces to

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The constraint $M_{t}^{q}(y)=0$ for $q=\sum_{i=1}^{n} x_{i}-N$ reduces to

$$
N y_{S}=\sum_{i=1}^{n} y_{S \cup\{i\}}
$$

for all subsets $S$ of $\{1, \ldots, n\}$ of cardinality at most $2 t-1$

## Reducing the number of constraints

Lemma Let $t \geq 1$ and $y \in \mathbb{R}^{I_{2 t}}$. If
$y_{\emptyset}=1 \quad$ and $\quad N y_{S}=\sum_{j=1}^{n} y_{S \cup\{j\}} \quad$ for all $\quad S \in I_{2 t-1}$,
then

$$
\sum_{S \in I_{=i}} y_{S}=\binom{N}{i} \quad \text { for all } \quad 0 \leq i \leq 2 t
$$

The hierarchy reduces to

$$
\inf \left\{\sum_{1 \leq i<j \leq n} W_{i, j} y_{\{i, j\}}: y_{\emptyset}=1, M_{t}^{1}(y) \succeq 0, \sum_{S \in I_{=i}} y_{S}=\binom{N}{i} \text { for } 0 \leq i \leq 2 t\right\}
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## Finite convergence

This potentially makes the hierarchy weaker, but we can still prove finite convergence to the optimal energy in $N$ steps

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This hierarchy can be generalized from $\{1, \ldots, n\}$ to $S^{n-1}$, where it still converges in $N$ steps

## Question 2

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We may assume $K$ is invariant under the symmetry group of the optimization problem

## Schoenberg's theorem

If $K \in \mathcal{C}\left(S^{n-1} \times S^{n-1}\right)$ is an $O(n)$-invariant positive definite kernel, then

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K(x, y)=\sum_{k=0}^{\infty} c_{k} P_{k}^{n}(x \cdot y)
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What if we wouldn't know about Schoenberg's theorem?

## Bochner's theorem

The action of $O(n)$ on $S^{n-1}$ defines an action on $\mathcal{C}\left(S^{n-1}\right)$ :

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Bochner's theorem says: $K(x, y)=\sum_{k} c_{k} \sum_{j=1}^{d_{k}} Y_{k}^{j}(x) Y_{k}^{j}(y)$
The addition formula: $\sum_{j=1}^{d_{k}} Y_{k}^{j}(x) Y_{k}^{j}(y)=P_{k}^{n}(x \cdot y)$

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Bochner's theorem says

$$
K(x, y)=\sum_{\pi}\left\langle C_{\pi}, Z_{\pi}(x, y)\right\rangle,
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where

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Here $C_{\pi}$ is a positive semidefinite matrix

## Question 3

How do we deal with inequality constraints?

## Sums-of-squares

For a polynomial optimization problem

$$
P=\inf \{p(x): x \in S(Q)\}, \quad S(Q)=\left\{x \in \mathbb{R}^{n}: q(x) \geq 0 \text { for } q \in Q\right\}
$$

we first need to reformulate as

$$
P=\sup \{c: p(x)-c \geq 0 \text { for } x \in S(Q)\}
$$

to use sums-of-squares

## Sums-of-squares

The Delsarte bound:

$$
\begin{aligned}
& \inf \left\{1+f(1): f(u)=\sum_{k=0}^{d} c_{k} P_{k}^{n}(u),\right. \\
& c_{0}, c_{1}, \ldots, c_{d} \geq 0, \\
& f(u) \leq-1 \text { for } u \in[\cos \theta, 1]\} .
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$$

The set $[\cos \theta, 1]$ is semialgebraic, e.g.,

$$
\begin{aligned}
& {[\cos \theta, 1]=\{x \in \mathbb{R}: x-\cos \theta \geq 0,1-x \geq 0\}, \text { or }} \\
& {[\cos \theta, 1]=\{x \in \mathbb{R}:(x-\cos \theta)(1-x) \geq 0\}}
\end{aligned}
$$

## Sums-of-squares

Here we do not need Putinar's theorem, an older result by Lukács says

$$
p(x) \geq 0 \text { for } x \in[\cos \theta, 1]
$$

implies

$$
p \in \mathcal{M}_{(\operatorname{deg}(p)-1) / 2}(\{x-\cos \theta, 1-x\})
$$

if $\operatorname{deg}(p)$ is odd, and

$$
p \in \mathcal{M}_{\operatorname{deg}(p) / 2-1}(\{(x-\cos \theta)(1-x)\})
$$

if $\operatorname{deg}(p)$ is even

## Semidefinite programs with semialgebraic constraints

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If these polynomials have symmetries we can use symmetric sums-of-squares which is more efficient (see the paper by Gatermann and Parrilo)

Computations for energy minimization

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- The second step of the hierarchy is numerically sharp (it gets at least 28 decimal digits of the ground state energy correct)


## Advertisement

PhD position in Delft: www.daviddelaat.nl/vacancy.html Application deadline: 1 October 2020

## Papers

Jean B. Lasserre, Global Optimization with Polynomials and the Problem of Moments, SIAM J. Optim., 11(3), 796-817, 2001

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Karin Gatermann, Pablo A. Parrilo, Symmetry groups, semidefinite programs, and sums of squares, Journal of Pure and Appl. Algebra, Vol. 192, No. 1-3, pp. 95-128, 2004

David de Laat, Frank Vallentin, A semidefinite programming hierarchy for packing problems in discrete geometry, Math. Program., Ser. B 151 (2015)

David de Laat, Moment methods in energy minimization: New bounds for Riesz minimal energy problems Trans. Amer. Math. Soc. (2019)

