Food Image Analysis: The Big Data Problem You Can Eat!

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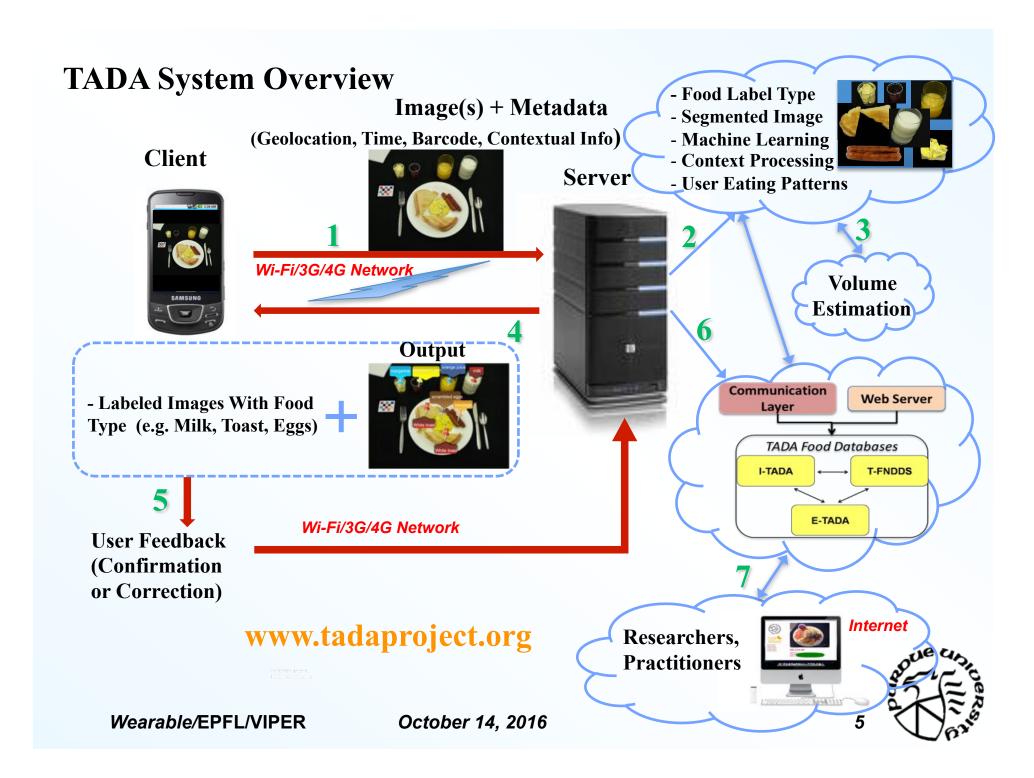
www.tadaproject.org

Research Team

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- Fengqing Zhu
- Students
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- Acknowledge the National Institutes of Health, Curtin University, CTSI, Purdue Research Foundation



Measuring accurate dietary intake is considered to be an open research problem

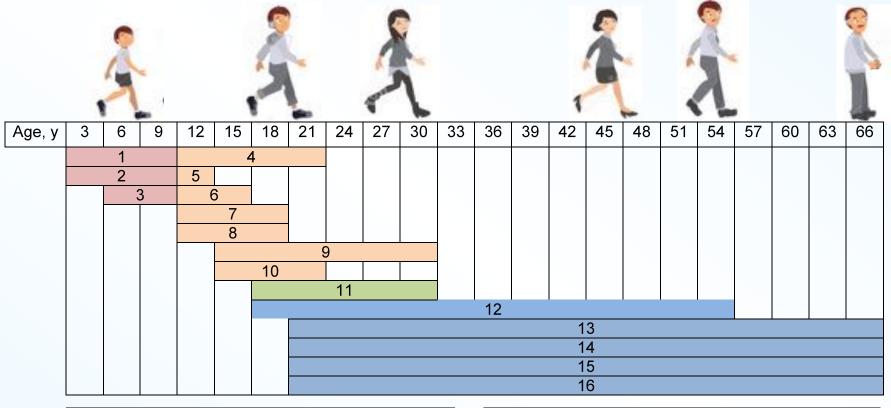


User Studies

- We have completed a total of 15 user studies
 - Free-living environment
 - More than 900 participants
 - More than 70,000 images acquired
- Each food image captures a real eating scene consists of multiple food items
- We have published more than 30 conference papers and 18 journal papers published since 2008 (detailed information at: www.tadaproject.org)



Summary of Studies: Completed or In Process



Study	Age range,	Sample	Supervised,	Community,
number	у	size	EO	# of days
1	3-10	63	1-4	
2	3-10	63		4
3	7-10	12		2
4	10-21	19		4
5	11-13	69		3
6	11-15	41	9-11	
7	11-18	63	2	
8	11-18	15	24 hr	
14/		7		1

Study	Age range,	ge range, Sample Supe		Community,
number	у	size	EO	# of days
10	14-21	18		56-58
11	18-30	247		8
12	18-55	20		8
13	20-70	77		8
14	21-65	57	2	A
15	21-65	45		7 8
16	21-65	22		22 3 7
ΔΙΙ	3_70	890	1_11	2-58

Wearable/ERFL/VIPER -- October 14, 2016

KEY: y=years, EO=eating occasions

	Community Dwelling							
Day 0	Day 1	Day 2	Day 3	Day 4	Day 5	Day 6	Day 7	Day 8
Thu	Fri	Sat	Sun	Mon	Tues	Wed	Thu	Fri
n = 46							n = 45	
User training & mobile telephone	Men = 15 (33%) Women = 30 (67%) Mean age = 32 y (range: 21-63 y)						Return mobile telephone	





Food in Focus

technology assisted dietary assessment

October 14, 2016

University of Hawaii: Study Eating Behaviors of Children In Guam

Before eating



After eating



How old is this participant?

9 years old!

October 14, 2016



TADA Color Fiducial Marker

- TADA color fiducial marker is a reference for food classification and portion estimation:
 - Geometric reference
 - Color reference
 - Image quality reference
- Real time image quality check is implemented on the mobile phone

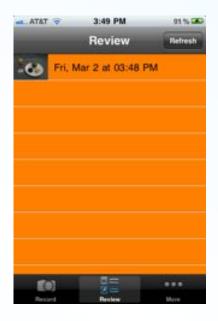


TADA color fiducial marker

TADA App









Apple (iOS8 and iOS9) – iPhone, iPod, iPad

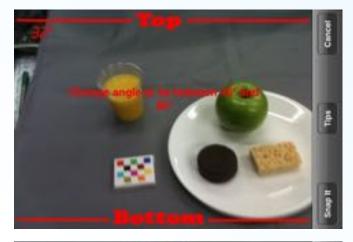
Android (4.3 and above) – phones and tablets

API and SDK are available for various parts of the TADA architecture



Image Acquisition

- Angle information is obtained from the phone
- Colors along with words assist the user in taking an image at the preferred angle



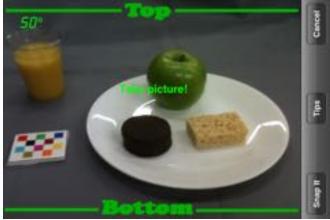
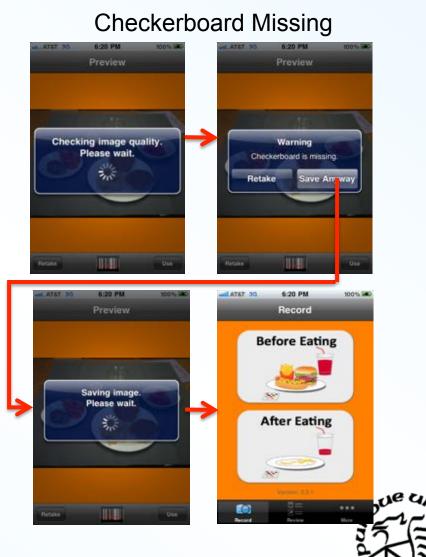
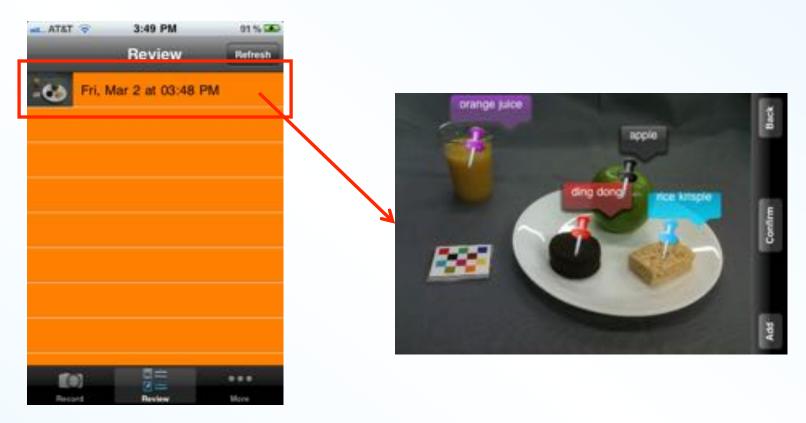


Image Quality Checking

- Check for:
 - Presence of fiducial marker (checkerboard)
 - Blurry image



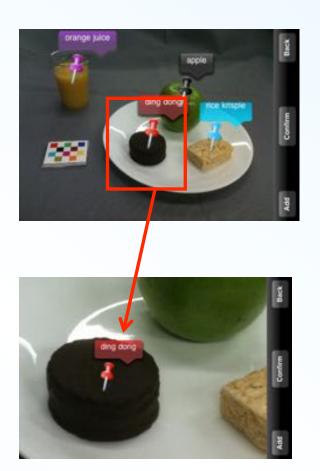
Review



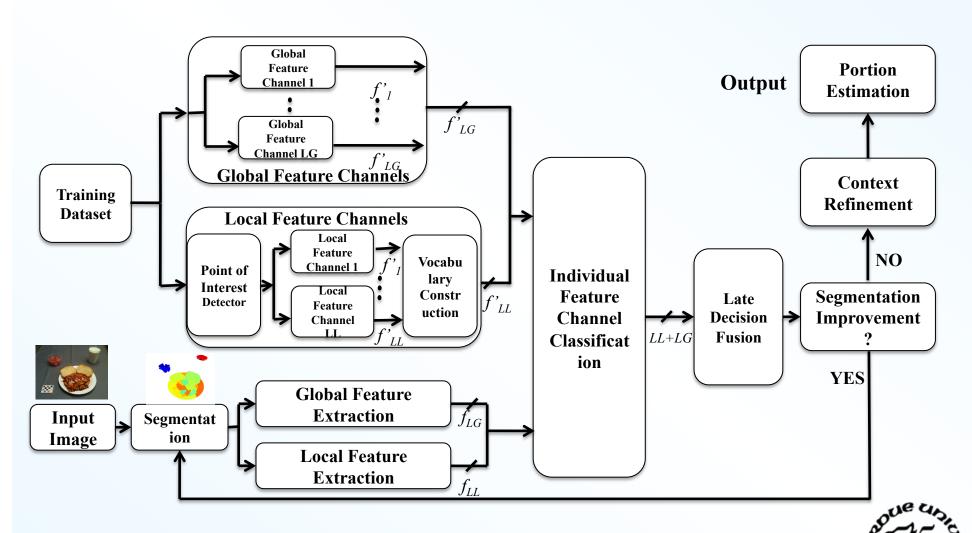
- The user can select an eating occasion from the list to review
- The before eating image is then displayed in landscape view with food labels on it

Review

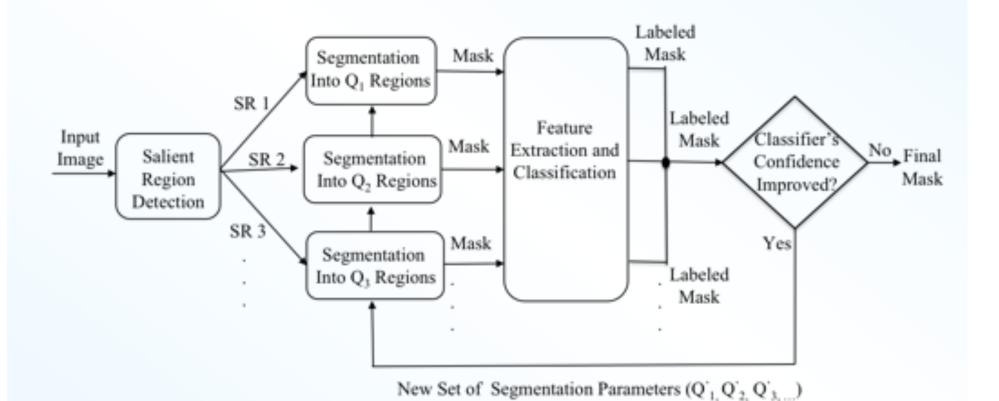
- Different colors help the user in identifying bubble-pin correspondence
- The green color is reserved for confirmed labels
- Zoom-in by pinching the screen to have a better view



TADA Image Analysis System

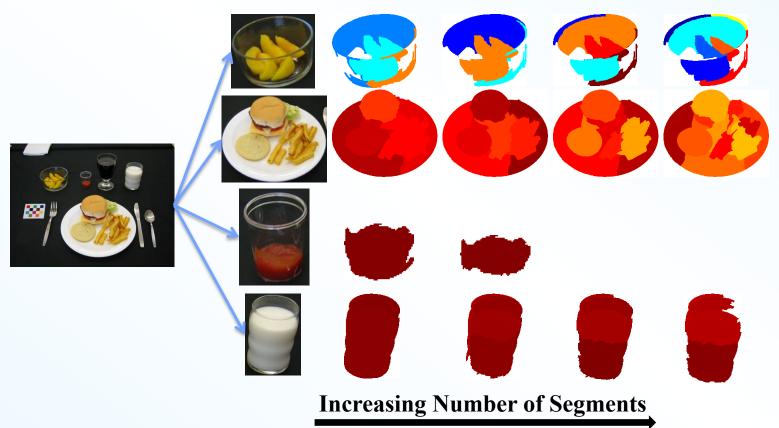


Multiple Hypothesis Segmentation and Classification (MHSC)

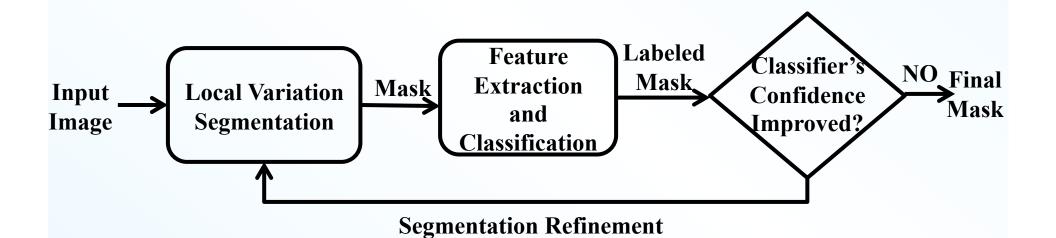


Segmentation

• Multiscale normalized cut



Simplified Multiple Hypothesis Segmentation and Classification



Segmentation

Local variation









Original Images

Local Variation

• Internal difference of a segmented region

$$Int(A) = \max_{e \in MST(A,E)} \omega(e)$$

• Difference between two segmented regions

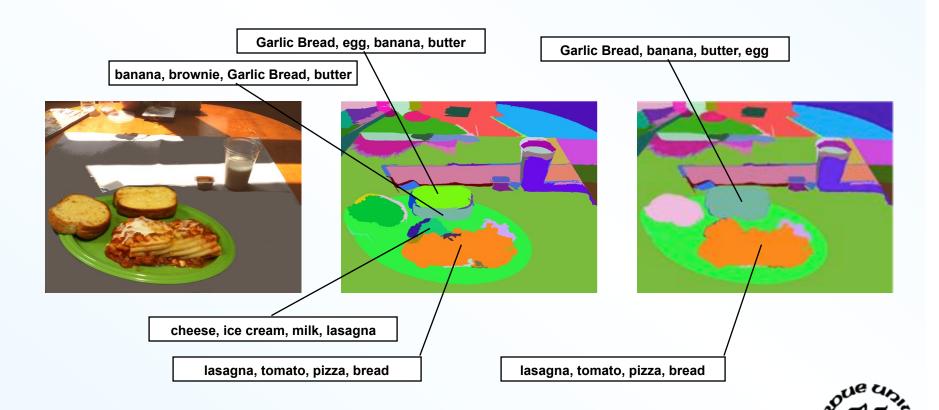
$$Dif(A,B) = \min_{p \in A, q \in B, (p,q) \in E} \omega(p,q)$$

• Two regions are segmented if

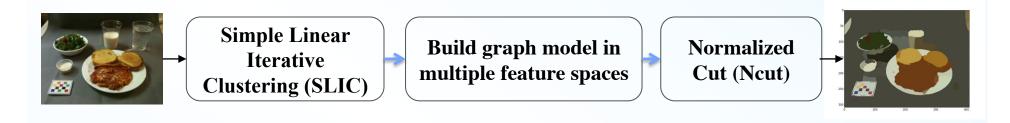
$$Dif(A,B) > \min(Int(A) + \frac{k}{|A|}, Int(B) + \frac{k}{|B|})$$

Segmentation Refinement

• Over-Segmentation



Superpixel Based Segmentation



- Use SLIC to get initial segments
- Use graph model to identify adjacent patches
- Create G=(V,E) based on the super pixels
 - Node: superpixel
 - Edge: similarity based on multiple cue (color, proximity and texture)
- Use Ncut on G

Segmentation Comparisons



Original Image



SLIC superpixels



SNcut at ODS



SNcut at OIS



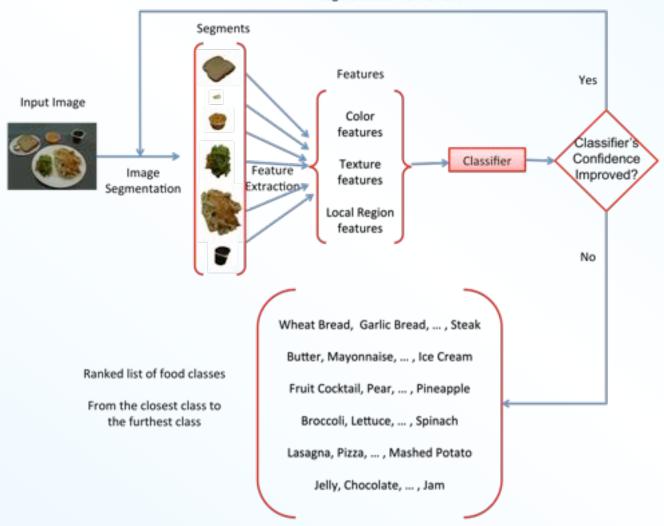
Local Variation



Hierarchical Segmentation

Features

Segmentation Refinement

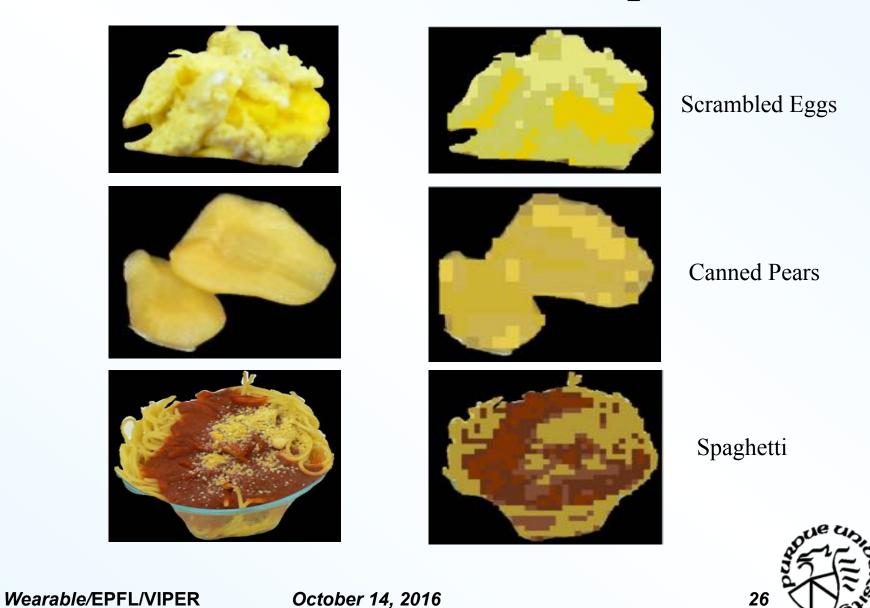


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Global Features: Color

- Color information is the key feature to identify foods like liquids, or to distinct between objects (e.g. mustard and ketchup)
- Foods show large variation of color:
 - Homogeneous vs. heterogeneous color distribution
 - Color irregularities (e.g. green vs. ripe fruit)
- Investigated 3 color feature channels:
 - Global color statistics
 - Entropy color statistics
 - Predominant color statistics

Predominant Color Examples



Global Features: Texture

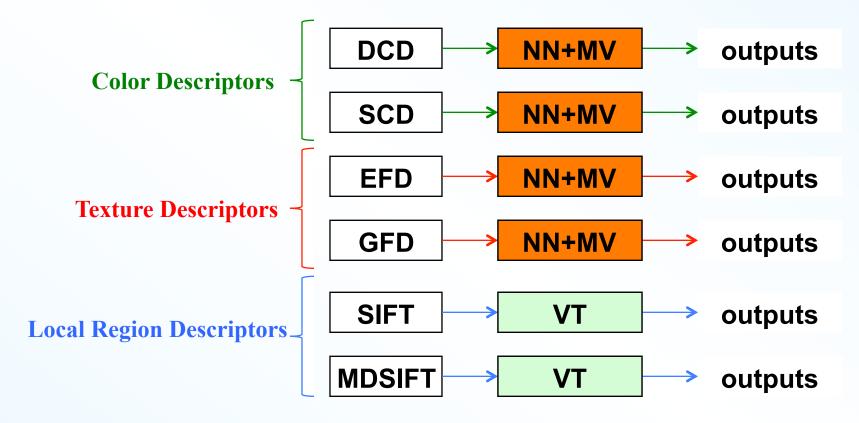
- Examined texture features for foods
- Proposed three texture descriptors:
 - Gradient Orientation Spatial-Dependence Matrix (GOSDM)
 - Entropy-based categorization and Fractal Dimension (EFD)
 - Gabor-based image decomposition and Fractal Dimension (GFD)
- Compared with widely used texture features:
 - GLCM
 - Gabor
 - Multifractal Spectrum (MFS)



Features Used

- Scalable Color Descriptor (SCD)
- Dominant Color Descriptor (DCD)
- Entropy-Based Categorization and Fractal Dimension
 Estimation (EFD)
- Gabor-Based Image Decomposition and Fractal Dimension Estimation (GFD)
- Scale Invariant Feature Transform (SIFT)
- Multi-scale Dense SIFT (MDSIFT)

Feature Classifier

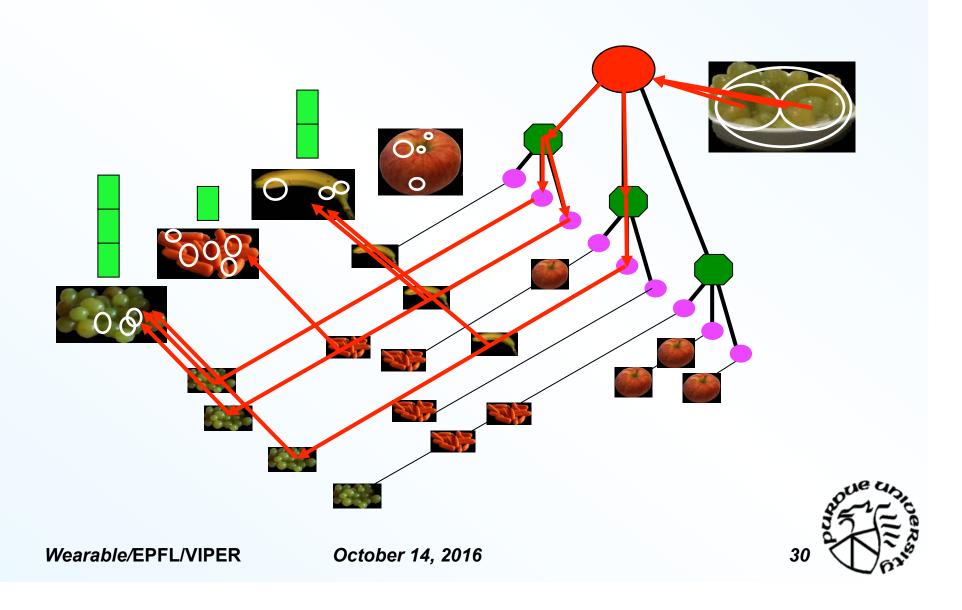


Note: NN: nearest neighbor

MV: majority vote

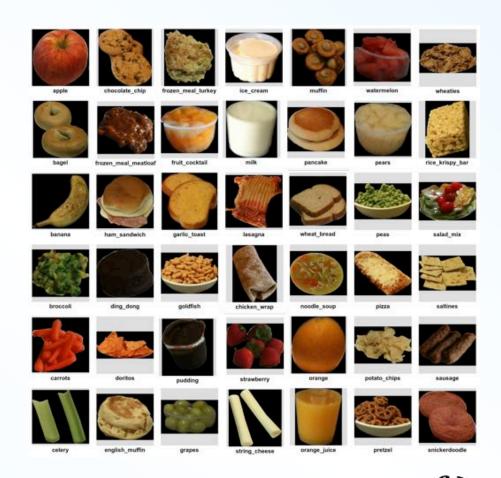
VT: vocabulary tree

Classification Using A Vocabulary Tree

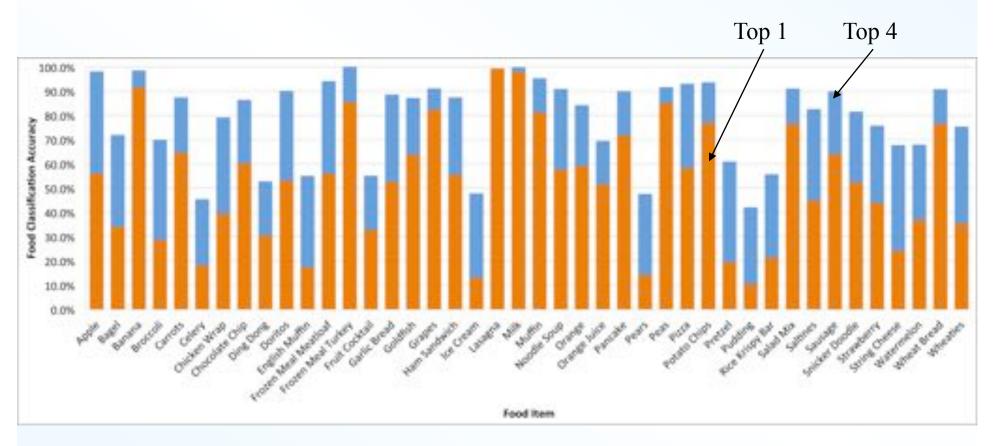


Classification Experiments

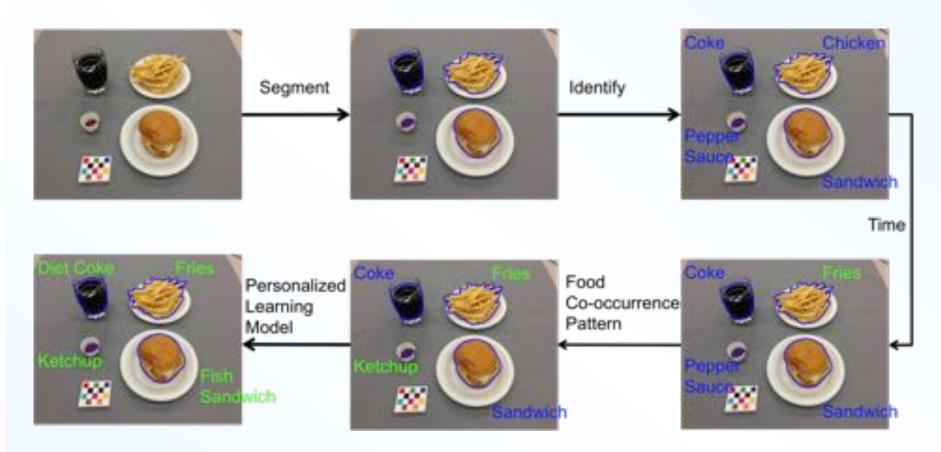
- Test Images: 1453 food images taken by 45 participants in natural eating conditions
- Train Images: 20 30 images per food class
- 42 food classes



Classification Accuracy of Foods



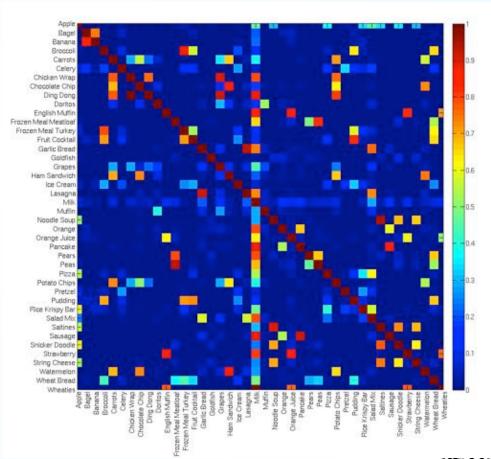
The Use of Contextual Information



- Time-based food consumption frequency
- Food co-occurrence patterns
- Date, time, place, dietary habits (patterns), work/ sleep patterns Wearable/EPFL/VIPER October 14, 2016

Food Co-Occurrence Patterns

- The likelihood of food combinations — their mutual probability of existing together in a single eating occasion
- A post-processing stage to promote agreement between the segment labels



Food Co-Occurrence Patterns

- Build a fully connected undirected graph between all segments
- Adjust the probability of each node by its association with all other nodes

$$p'(f_k|S_n) = \frac{p(f_k|S_n)A(f,S)}{Z(\phi,S_1,...,S_N)}$$

$$A(f,S) = \exp(\sum_{i=0}^4 \sum_{j=1,j\neq n}^N \phi(f_{k,n},f_{i,j})p(f_i|S_j))$$

 $p(f_1|S_3) p(f_2|S_3)$ $p(f_1|S_4) p(f_2|S_4)$ $p(f_3|S_3) p(f_4|S_3)$ $p(f_3|S_4) p(f_4|S_4)$ where $p(f_k|S_n)$ is the probability of the food label f_k for segment S_n

Clique 3

Clique 1

 $p(f_1|S_1) p(f_2|S_1)$

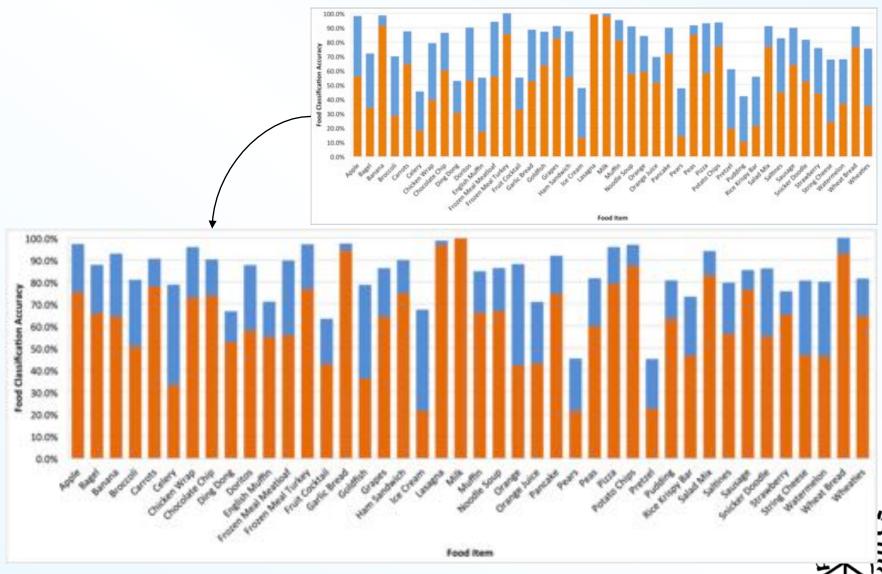
 $p(f_3|S_1) p(f_4|S_1)$

Clique 2

 $p(f_1|S_2) \quad p(f_2|S_2)$

Clique 4

Food Co-Occurrence



Temporal Context

Recursive Bayesian Model of Food Consumption Frequency

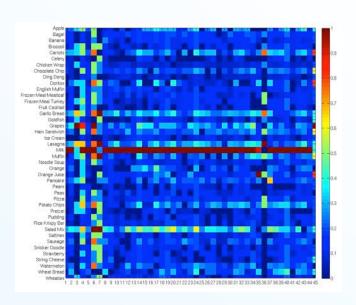
- Let $p_{\lambda i}$ (x^k) be the probability density function (PDF) representing S_j consumes λ_i on the k^{th} day, and z^k be the observation whether S_j consumes λ_i on the k^{th} day
- z^k is obtained from the user feedback in the TADA system
- Posteriori update:

$$p_{\lambda_{i}}(x^{k} \mid z^{1:k}) = \frac{p_{\lambda_{i}}(x^{k} \mid z^{k})p_{\lambda_{i}}(x^{k} \mid z^{1:k-1})}{p_{\lambda_{i}}(z^{k} \mid z^{1:k-1})} = \frac{likelihood \times prior}{normalization}$$

• On the k+1th day, $P_{\lambda i}$ is computed as $P_{\lambda i}$ = arg max $p_{\lambda i}$ (x^k) $z^{1:k}$)

The Use of Temporal Context

- Selected participants with similar food consumption patterns were used to build personalized eating datasets for a month
- Three separate datasets (i.e. dataset 1, 2 and 3) with a total of 358 food images from a free-living study



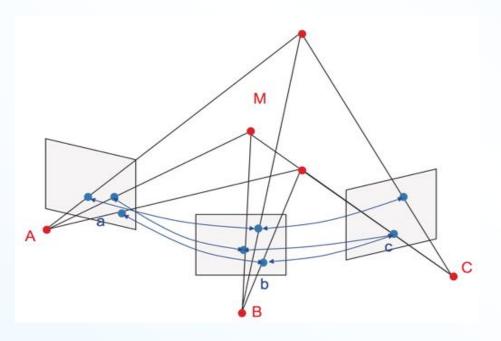
statistics	user ID	with context	without context	
average daily	user1	61.88	53.23	
classification	user2	65.25	62.90	
accuracy(%)	user3	59.69	53.28	
average daily	user1	1	18.45	
accuracy	user2	3.85		
improvement(%)	user3	12.39		

Food Portion Estimation: Single-View

- To reduce a user's burden, our work has focused on the use of a single image to estimate food portion
- Food portion estimation based on a single-view is an illposed inverse problem
 - Most 3D information has been lost during projection process
- We use pre-defined geometric models to estimate food portion size

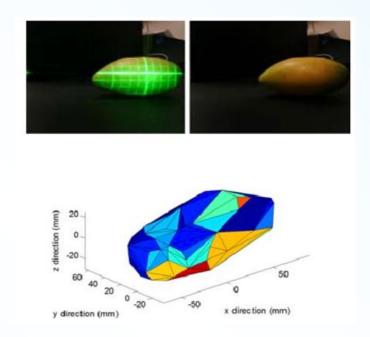
Food Portion Estimation: Stereo and 3D Approaches

multiple images



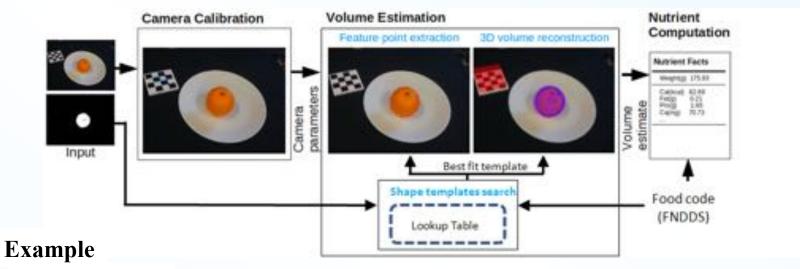
(C. Xu, Ph.D. thesis at Purdue University, May 2014)

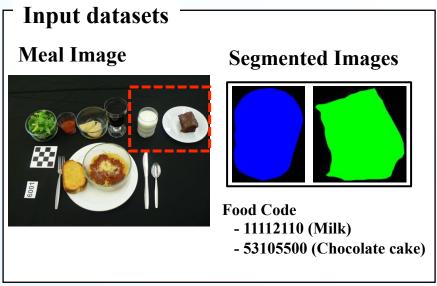
3D range images

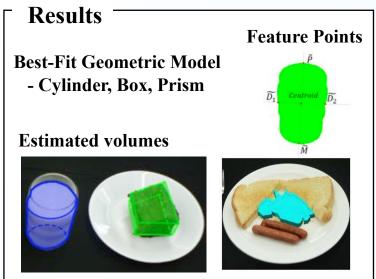


(J. Shang et al., ICCV Workshop '11)

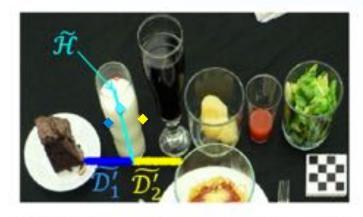
Food Volume Estimation



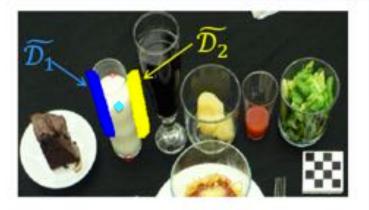




Iterative Points Search for Cylinder Model



 (a) Initial search region for radius and height in rectified image coordinates.



(b) Refined search region for radius in rectified image coordinates.

Candidates obtained

Project candidate points

Adjust the increment along radius and height, till projection error has been minimized

Food Portion Estimation: Points Search

- For example, many food containers are either cylinders or can be approximated to be cylinders
- To estimate portion size only radius and height are required
- A points search technique is designed to have radius and height estimated by minimizing projection error across coordinates

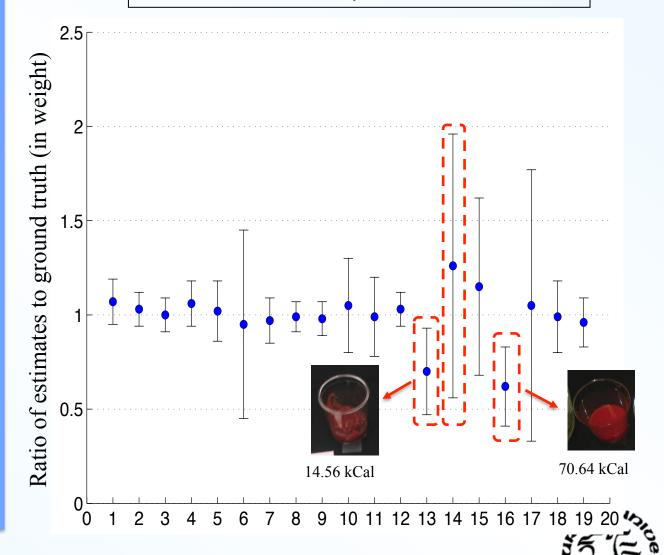
Food Items

- 1.2% Milk
- 2. Sausage links
- 3. Scrambled eggs
- 4. Toast
- 5. Garlic bread
- 6. Chocolate cake w/ icing
- 7. Sugar cookie
- 8. Spaghetti w/ sauce, cheese
- 9. Orange juice
- 10. Peach slices
- 11. Pear, canned halves
- 12. French fries
- 13. Ketchup
- 14. Lettuce (salad)
- 15. Margarine
- 16. French dressing
- 17. Strawberry jam
- 18. Coke
- 19. Cheeseburger sandwich

Fang *et al.* ISM 2015

Wearable/EPFL/VIPER

Ratio greater than one, overestimated Ratio less than one, underestimated



Food And Nutrient Database For Dietary Studies (FNDDS)

- FNDDS is a database that provides energy, nutrients for typical portions for foods/beverages
- The newest version of FNDDS (FNDDS 2011-2012)
 contains 7,600 main foods/beverages and 9,900 additional
 foods/beverages associated with a specific main food/
 beverage
- More information can be found at: www.ars.usda.gov/ba/bhnrc/fsrg



Food Density

Density
$$(g/cm^3) = \frac{\text{Weight } (g)}{\text{Volume } (cm^3)}$$

• True density: density of pure substance or material calculated from its component densities



• Apparent density: density of a particle including all pores

- Bulk density: density when particles are packed or stacked in bulk including void spaces



The Estimated Energy For A Meal

• Three sample meals^[1]



Combination type A: average ratio of estimated energy to ground truth: 1.01



Combination type B: average ratio of estimated energy to ground truth: **0.97**



Combination Type C: average ratio of estimated energy to ground truth: **1.06**

[1]: "Single-View Food Portion Estimation Based on Geometric Models", S. Fang et al. ISM 2015



TADA Databases

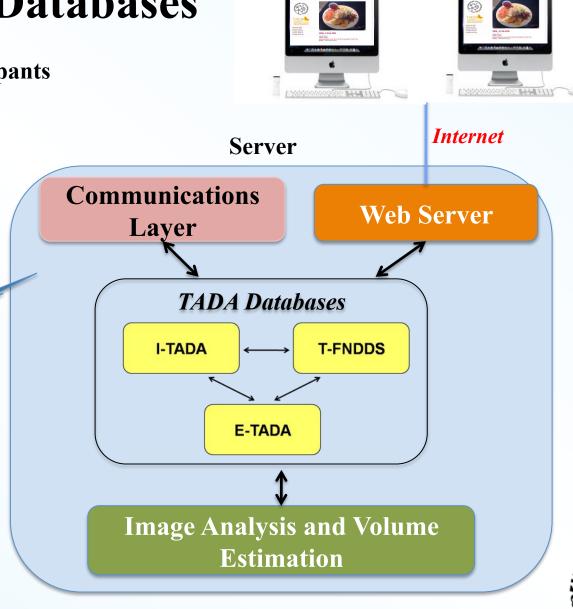
Users/Patients/Participants



Wi-fi/3G/4G







Nutritionist/Dietitian/Researchers

Wearable/EPFL/VIPER

October 14, 2016

Multi-Food Image Analysis With Deep Learning

- TADA system has been tested and validated by more than 800 users who took 60,000+ food images
- VIPER-FoodNet (VFN) dataset: 300,000+ food images from the net verified by crowdsourcing ongoing
- Hierarchical, auto-associative food recognition
- Semantic segmentation
- Depth prediction from a single image
- From supervised learning to unsupervised learning (handle large number of classes)



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