

# Probabilistic Graphical Models

## Lecture 11: Convex Inference Relaxations. LP Relaxations

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- Why convex relaxation?
  - Unique solution. Know when you're done
  - Robust under small data changes (f.ex.: experimental design)
  - Statistical advantages

Wainwright, JMLR 7 (2006)

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  - Robust under small data changes (f.ex.: experimental design)
  - Statistical advantages
- Exact inference convex. Are convex relaxations also tighter?  
 $\Rightarrow$  Unfortunately not ((G)LBP hard to beat)

Wainwright, JMLR 7 (2006)

# Convex Relaxations: The Recipe

$$\log Z = \max_{\mu \in \mathcal{M}} \left\{ \boldsymbol{\theta}^T \boldsymbol{\mu} + H[\boldsymbol{\mu}] \right\}$$

$$\mathcal{M} = \left\{ (\boldsymbol{\mu}_j) \mid \boldsymbol{\mu}_j = \mathbb{E}_Q[\mathbf{f}_j(\mathbf{x}_{C_j})] \text{ for some } Q(\mathbf{x}) \right\}$$

$\mathcal{M}$  can be hard to fence in  
 $\boldsymbol{\theta} \leftrightarrow \boldsymbol{\mu}$  can be hard to compute  
 $H[\boldsymbol{\mu}]$  can be hard to compute

F2

# Convex Relaxations: The Recipe

$$\log Z \leq \max_{\tau \in \mathcal{M}} \left\{ \boldsymbol{\theta}^T \boldsymbol{\tau} + \tilde{H}[\boldsymbol{\tau}] \right\}, \quad \boldsymbol{\mu} = \boldsymbol{\tau}_K, \quad \boldsymbol{\theta}_{\setminus K} = \mathbf{0},$$

$$\mathcal{M} = \left\{ (\boldsymbol{\mu}_j) \mid \boldsymbol{\mu}_j = \mathbb{E}_Q[\mathbf{f}_j(\mathbf{x}_{C_j})] \text{ for some } Q(\mathbf{x}) \right\}$$

- Recipe for **convex** relaxation

- 1 Concave upper bound  $\tilde{H}[\boldsymbol{\tau}]$  to entropy  $H[\boldsymbol{\mu}]$ , tractable function of pseudomarginals  $\boldsymbol{\tau}$  (small enough, but  $\boldsymbol{\mu} = \boldsymbol{\tau}_K$ )

F2b



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- 2 Convex outer bound  $\tilde{\mathcal{M}} = \{\boldsymbol{\tau}\} \supset \mathcal{M}$  (f.ex.:  $\mathcal{M}_{\text{local}}$ )

F2c

# Convex Relaxations: The Recipe

$$\log Z \leq \max_{\tau \in \tilde{\mathcal{M}}} \left\{ \theta^T \tau + \tilde{H}[\tau] \right\},$$

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- Recipe for **convex** relaxation

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- Notes

- Convex optimization. Upper bound to  $\log Z$  (not lower, like MF)
- $\tau$  can have more components than  $\mu$  (clique marginals).  
Embedding:  $\mu = \tau_K$ ,  $H[\tau] = H[\mu]$ ,  $\mathcal{M} = \{\tau \mid \tau_K = \mu \in \mathcal{M}\}$
- Must have  $H[\tau] \leq \tilde{H}[\tau]$  for all  $\tau \in \mathcal{M}$  ( $\Leftrightarrow \tau_K \in \mathcal{M}$ )

# Examples for Convex Relaxations

$$\log Z \leq \max_{\tau \in \tilde{\mathcal{M}}} \left\{ \boldsymbol{\theta}^T \boldsymbol{\tau} + \tilde{\mathbf{H}}[\boldsymbol{\tau}] \right\}$$

- Tree-reweighted belief propagation  
 ⇒ Exercise sheet

[Wainwright *et.al.*, UAI 02]

- Conditional entropy decomposition

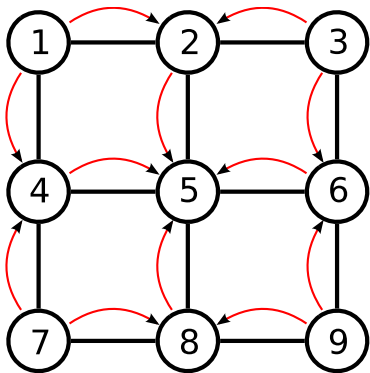
[Globerson *et.al.*, AISTATS 07]

F3

$$\begin{aligned} H[P(\mathbf{x})] &= \sum_i H[P(x_i | \mathbf{x}_{<i})] \leq \sum_i H[P(x_i | \mathbf{x}_{S_i})], \\ S_i &\subset \{1, \dots, i-1\}, S'_i = S_i \cup \{i\} \end{aligned}$$

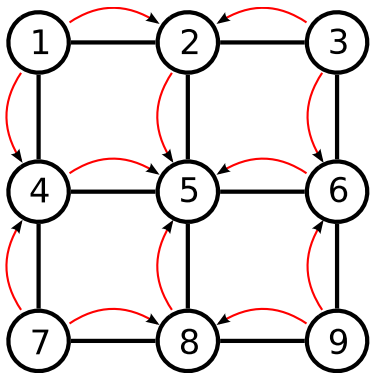
And:  $P(\mathbf{x}_{S'_i}) \mapsto H[P(x_i | \mathbf{x}_{S_i})] = H[P(\mathbf{x}_{S'_i})] - H[P(\mathbf{x}_{S_i})]$  **concave!**

# Conditional Entropy Decomposition



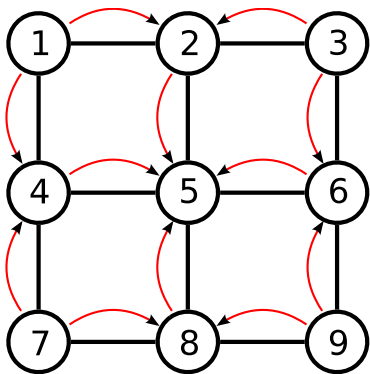
$$\begin{aligned}
 H[\tau] = & H_1 + H_{3|1} + H_{7|13} + H_{9|137} + H_{2|1379} + \\
 & H_{4|13792} + H_{6|137924} + \\
 & H_{8|1379246} + H_{5|13792468}
 \end{aligned}$$

# Conditional Entropy Decomposition



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 H[\tau] \leq & H_1 + H_3 + H_7 + H_9 + H_{2|13} + \\
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$$\begin{aligned}
 H[\tau] \leq & H_1 + H_3 + H_7 + H_9 + H_{213} - H_{13} + \\
 & H_{417} - H_{17} + H_{639} - H_{39} + \\
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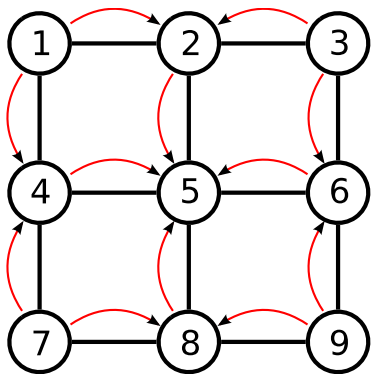
Here,  $H_S := H[\tau_S]$ . Relaxation:

$$H_3 \geq H_{3|1}, H_7 \geq H_{7|13}, H_9 \geq H_{9|137}, \dots$$

Index set for  $\tau$ :

- Nodes, edges ( $\mu$ )
- $\{13, 17, 39, 79\}$
- $\{213, 417, 639, 879\}, \{52468, 2468\}$

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**Note:** In general ( $\neq$  tree), relaxation cannot be avoided

# Semidefinite Relaxations

$$\mathcal{M} = \left\{ (\boldsymbol{\mu}_j) \mid \boldsymbol{\mu}_j = \mathbb{E}_Q[\mathbf{f}_j(\mathbf{x}_{C_j})] \text{ for some } Q(\mathbf{x}) \right\}, \quad \mathbf{x} \in \{0, 1\}^m$$

Binary MRF. Pairwise and single node potentials ( $|C_j| \leq 2$ )

- So far: Fencing in  $\mathcal{M}$  by **linear** inequalities (larger polytope).

$$\{\mathbf{A} \mid \mathbf{A} \succeq \mathbf{0} \text{ (pos. semidef.)}\} \Leftrightarrow \{\mathbf{A} \mid \text{tr } \mathbf{A} \mathbf{x} \mathbf{x}^T \geq 0 \quad \forall \mathbf{x}\}$$

1 SD constraint:  $\infty$  many linear constraints! Still tractable



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- SD outer bound: If  $\boldsymbol{\mu} \in \mathcal{M}$ , then

$$\mathbb{E}_Q \left[ \begin{pmatrix} 1 \\ \mathbf{x} \end{pmatrix} (1 \ \mathbf{x}^T) \right] = \mathbf{M}_1(\boldsymbol{\mu}) \succeq \mathbf{0} \quad \Rightarrow \quad \boldsymbol{\mu} \in \mathcal{S}_1 = \{\boldsymbol{\mu} \mid \mathbf{M}_1(\boldsymbol{\mu}) \succeq \mathbf{0}\}$$

First-order SD outer bound (convex cone)

F10

- Can use intersection with  $\mathcal{M}_{\text{local}}$
- Higher-order possible ( $\mathbf{g}(\mathbf{x})$  instead of  $\mathbf{x}$ )

## Semidefinite Relaxations (II)

$$\mathcal{M} \subset \mathcal{S}_1 = \{\boldsymbol{\mu} \succeq \mathbf{0} \mid \mathbf{M}_1(\boldsymbol{\mu}) \succeq \mathbf{0}\}$$

How about the entropy  $H[\boldsymbol{\mu}]$  (need concave upper bound)?

- For **continuous**  $\tilde{\mathbf{x}}$ : Gaussian maximizes (differential) entropy

$$H[P(\tilde{\mathbf{x}})] = - \int P(\tilde{\mathbf{x}}) \log P(\tilde{\mathbf{x}}) d\tilde{\mathbf{x}} \leq (1/2) \log |2\pi e \text{Cov}_P[\mathbf{x}]|$$

[recall lecture 3]. Covariance is part of  $\mathbf{M}_1(\boldsymbol{\mu})$

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- $\mathbf{x}$  discrete  $\rightarrow \tilde{\mathbf{x}}$  continuous by reverse quantization

F11

$$\tilde{\mathbf{x}} = \mathbf{x} + \mathbf{u}, \quad u_j \sim U([-1/2, 1/2]), \quad \underbrace{P(\tilde{\mathbf{x}})}_{\text{density}} = \underbrace{P(\mathbf{x}(\tilde{\mathbf{x}}))}_{\text{distribution}}$$

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- Convex semidefinite inference relaxation

Wainwright, Jordan, IEEE SP 54(6)

- Tighter than LBP. Better marginal approximations
- Much more expensive (no local belief propagation solver)

# Convexity of (reweighted) Bethe

$$P(\mathbf{x}) \approx \frac{\prod_j \mu_j(\mathbf{x}_{C_j})}{\prod_i \mu_i(x_i)^{n_i-1}}, \quad n_i = |\{j \mid i \in C_j\}|, \quad \mu \in \mathcal{M}_{\text{local}}$$

Recall Bethe approximation: Pretend  $\mathcal{G}$  was a tree

$\Rightarrow$  When is this convex? Convexification?

Energy term  $-\theta^T \mu$ ?

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Bethe neg-entropy  $-\text{H}_{\text{Bethe}}[\mu]$ ? **Not convex!**

$$-\text{H}_{\text{Bethe}}[\mu] = \underbrace{-\sum_j \text{H}[\mu_j(\mathbf{x}_{C_j})]}_{\text{convex (positive)}} + \underbrace{\sum_i (n_i - 1) \text{H}[\mu_i(x_i)]}_{\text{concave (negative)}}$$

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- Above: **Conditional** neg-entropy is convex ( $i \in C_j$ )!

F12

$$\mu_j(\mathbf{x}_{C_j}) \mapsto -\text{H}[\mu_j(\mathbf{x}_{C_j \setminus i}) \mid \mu_i(x_i)] = -\text{H}[\mu_j(\mathbf{x}_{C_j})] + 1 \cdot \text{H}[\mu_i(x_i)]$$



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- $\mathcal{G}$  tree: Nothing left. Hey: Bethe relaxation convex for trees! Knew that already:
  - Not relaxation, but **exact** then
  - And exact variational inference is convex

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- $\mathcal{G}$  has single cycle: Nothing left either [exercise sheet]
  - Bethe relaxation convex (solution usually not correct)
  - LBP always converges

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- **Convexify** Bethe relaxation by decreasing counting numbers  $n_i$  until “nothing left”
  - Reweighted Bethe relaxations solved by reweighted LBP
  - Somewhat lacks interpretability
  - TRW-BP (last exercise sheet) example with additional motivation

Heskes, JAIR 26 (2006)

# LP Relaxations

What about the mode (decoding)? Integer programming:

F14

$$\text{MAP} : \mathbf{x}_* = \operatorname{argmax} \log \left[ \mathbf{Z}^{-1} e^{\boldsymbol{\theta}^T \mathbf{f}(\mathbf{x})} \right] = \operatorname{argmax} \boldsymbol{\theta}^T \mathbf{f}(\mathbf{x})$$

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Linear criterion  $\Rightarrow$  Linear programming transformation

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$\Rightarrow$  Variational inference without entropy term

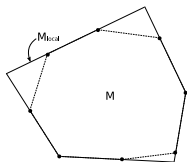
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- LP relaxations by outer bounds:  $\mathcal{M} \subset \mathcal{M}_{\text{local}}$

$\Rightarrow$  Result always a tractable LP.

Catch:  $\mathcal{M}_{\text{local}}$  too many extreme points  $\Rightarrow$  Fractional solutions

F14b



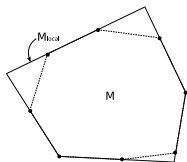
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- Key question: Does max-product solve this LP?

- For tree: Yes, and MP **is** a dual algorithm
- In general: No.

But (carefully) **reweighted** max-product does

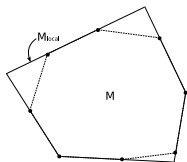
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- Why should I care?
  - For several NP-hard problems:  $\mathcal{M}_{\text{local}}$  “first order” LP relaxation frequently used
  - Reweighted MP: Fastest known algorithm in some cases

# Wrap-Up

- Convex variational relaxations: Concave upper bound to entropy, convex outer bound to marginal polytope
- Bethe problem can be convex (graph with  $\leq 1$  cycle). It can be convexified
- First-order LP relaxations by fast convergent reweighted max-product