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### Motivation

Introduction

### Image classification:

- Impossible to carry out terrain campaigns to obtain ground truth for every acquired image.
- ⇒ Intelligently reuse the information provided by labeled pixels from similar images.

#### Change detection:

- Ambiguity problem between changed and unchanged pixels.
- ⇒ Better representation of the images to highlight changed regions.

### Motivation

### Issues when analyzing multiple remote sensing images:

- different illumination.
- changing atmospheric conditions,
- varying acquisition geometry,
- seasonal effects.
- ⇒ shifted probability distributions between images.
- ⇒ need to **match/align the images**: physical models (atmospheric correction), histogram matching,...

### A concrete example: 2 QuickBird images of Zurich

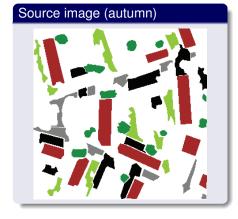
### Source image (autumn)

Introduction



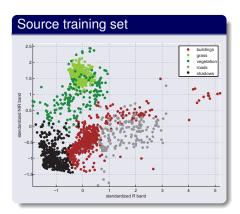
### Target image (summer)

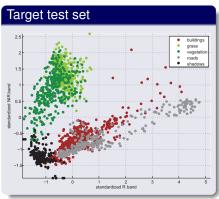






### Red vs NIR scatterplots





### Objectives

#### **Domain Adaptation** via feature extraction

- Map the two images into a feature space where the differences are reduced.
- Test different feature extraction methods (PCA, KPCA, TCA).

### Image classification:

⇒ Apply on the target image a classifier built on labeled source samples only.

#### Change detection:

⇒ Enhanced quality of the difference image.



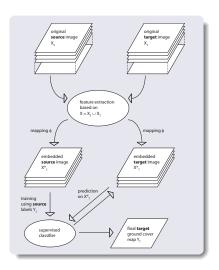
### Domain Adaptation via feature extraction: principle

- $\mathcal{D}_S = \{X_S, Y_S\} \rightarrow \text{labeled}$ source training data.
- $X_T \rightarrow$  unlabeled target data.
- Find a common mapping  $\phi$ (feature extraction techniques: PCA, KPCA, etc.):

$$X_S \to \phi(X_S) = X_S^*,$$
  
 $X_T \to \phi(X_T) = X_T^*.$ 

⇒ Reduce differences between distributions so that

$$P(X_S^*) \approx P(X_T^*). \checkmark$$



### Classification accuracy on target image



Target image



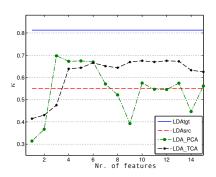
LDAsrc: K = 0.54



**LDAtgt**: K = 0.79

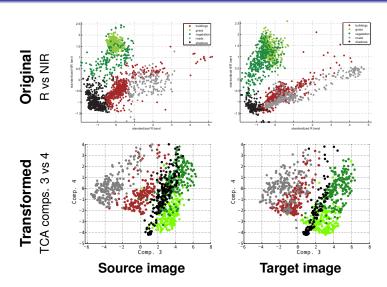


**LDA\_TCA**: K = 0.68



Gain of  $\sim$  0.15  $\kappa$  points over the Source model (average over 10 runs).

### Extracted features



### A multitemporal application: change detection

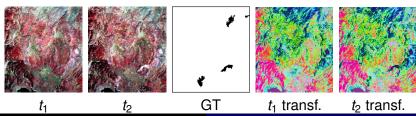
#### **Definitions**

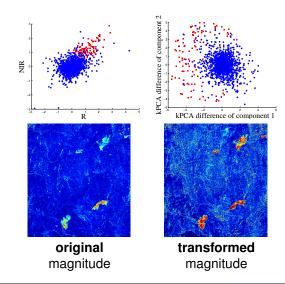
- Pixel-based comparison of (co-)registered images to detect spectral differences related to ground cover changes.
- Image differencing (Change Vector Analysis) is the most applied technique:
  - Magnitude of difference pixel vector  $\langle \theta \rightarrow No \text{ change} \rangle$ .
  - Magnitude of difference pixel vector  $> \theta \rightarrow$  **Change**.

### Image alignment in change detection

### Aligning unchanged areas

- Based on some 'no change' information (easy to obtain)
   match the distribution of images pre- and post-event.
- A common set of unchanged pixels, at same locations in both images, is used to extract the new projection.
- Physical meaning is lost, but pixel-wise comparison is improved.

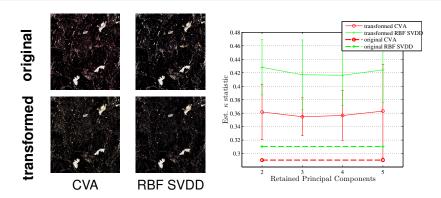




Even if the magnitude looks 'noisy' the separability between changes / no changes is increased!

### Change detection results

Introduction



 Improvements over the original space with different classification techniques:  $\sim$ 0.1  $\kappa$  points (average over 10 runs).

### Summing up

Introduction

• Feature extraction techniques efficiently align images in the feature space.

### Image classification:

- ⇒ newly acquired images can be suitably classified using already existing ground truth.
- ⇒ classifiers portability √

### Change detection:

- ⇒ the projection aligns unchanged pixels emphasizing changed regions.
- ⇒ enhanced changed detection √

### The end

Introduction

# Thank you for your attention!

## Any questions?

www.unil.ch/unisciences/GionaMatasci www.kernelCD.org

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