



# 1 Seidel's algorithm for unweighted undirected APSP

**Theorem 1.** *APSP in unweighted undirected  $n$ -node graphs can be computed in  $\mathcal{O}(n^\omega \log n)$  time.*

*Proof.* Given a graph  $G = (V, E)$  we first use fast matrix multiplication to compute graph  $G^2 = (V, E^2)$ , where

$$E^2 = \{(u, v) \mid (u, v) \in E \vee \exists_w (u, w) \in E \wedge (w, v) \in E\}.$$

We compute APSP recursively in  $G^2$ .

Since the diameter of each connected component halves with each recursive call, after  $\log n$  calls we are left with a collection of cliques – each shortest path is of length 0, 1, or  $\infty$ , and we can easily compute all of them in  $\mathcal{O}(n^2)$  time.

Now, given shortest paths  $D(u, v)$  in  $G^2$  we want to compute shortest paths  $d(u, v)$  in  $G$ . Note that either  $d(u, v) = 2D(u, v)$  or  $d(u, v) = 2D(u, v) - 1$ . We only need to distinguish between these two cases.

If  $d(u, v) = 2D(u, v)$ , then for all neighbors  $w$  of  $v$  there must  $D(u, w) \geq D(u, v)$  (do you see why?). On the other hand, if  $d(u, v) = 2D(u, v) - 1$ , then there must exist a neighbor  $w$  of  $v$  with  $D(u, w) = D(u, v) - 1$ , and for all neighbors  $w$  there must  $D(u, w) \leq D(u, v)$  (do you see why?).

Hence, we use fast matrix multiplication to compute the matrix  $Z$  such that

$$Z(u, v) = \sum_w D(u, w) \cdot \mathbb{1}[(w, v) \in E].$$

Now

$$d(u, v) = \begin{cases} 2D(u, v) & \text{if } Z(u, v) \geq \deg_v \cdot D(u, v), \\ 2D(u, v) - 1 & \text{if } Z(u, v) < \deg_v \cdot D(u, v). \end{cases}$$

□

**Exercise 1.** Which parts of this algorithm do not generalize to directed graphs?

## 2 Faster $(\min, +)$ -product for small integers

**Theorem 2.** *The  $(\min, +)$ -product of two  $n \times n$  matrices with entries in  $\{0, \dots, M\}$  can be computed in  $\tilde{\mathcal{O}}(Mn^\omega)$  time.*

*Proof.* Replace each input entry  $x$  with  $(n + 1)^x$ ; compute the standard  $(+, \cdot)$ -product; look at the least significant non-zero digits in  $(n + 1)$ -ary encodings of the output entries.

Transformed entries need  $M \log n$  bits to represent. Arithmetic operations (addition, subtraction, multiplication, division) on such numbers take  $\tilde{\mathcal{O}}(M \log n)$  time. Hence, the total running time is  $\tilde{\mathcal{O}}(Mn^\omega)$ . □

**Exercise 2.** Show that the above requirement that the entries are nonnegative can be easily circumvented.

**Exercise 3.** Does the above algorithm, together with the reduction from APSP to  $(\min, +)$ -product, yield a  $\tilde{\mathcal{O}}(Mn^\omega)$  time algorithm for APSP in directed graphs with weights in  $\{-M, \dots, M\}$ ?