# Discrete Optimization (Spring 2019)

# Assignment 3

## Problem 1

Show the "if" direction of the Farkas' lemma: given  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$ , if there exists a  $\lambda \in \mathbb{R}^m_{\geq 0}$  such that  $\lambda^\top A = 0$  and  $\lambda^\top b = -1$ , then the system  $Ax \leq b$  is unfeasible.

#### **Solution:**

Suppose that there exists  $x^* \in \mathbb{R}^n$  such that  $Ax^* \leq b$ . Then, since  $\lambda \geq 0$ , we have:

$$\lambda^{\top} A x^* \leq \lambda^{\top} b \implies 0 \leq -1,$$

a contradiction.

#### Problem 2

A polyhedron  $P = \{x \in \mathbb{R}^n : Ax \leq b\}$  contains a line, if there exists a nonzero  $v \in \mathbb{R}^n$  and an  $x^* \in \mathbb{R}^n$  such that for all  $\lambda \in \mathbb{R}$ , the point  $x^* + \lambda \cdot v \in P$ . Show that a nonempty polyhedron P contains a line if and only if A does not have full column-rank.

## **Solution:**

Assume that P contains a line  $\{x \in \mathbb{R}^n : x = x^* + \lambda \cdot v, \ \lambda \in \mathbb{R}\}$ . We claim that  $v \in ker(A)$ , i.e. for all rows  $a_i$  of A we have  $a_i^T v = 0$ . Assume for contradiction that there is a row  $a_i$  with  $a_i^T v \neq 0$ . Then we can choose  $\lambda \in \mathbb{R}$  such that  $a_i^T x^* + \lambda a_i^T v > b_i$  (namely such that  $|\lambda| > |\frac{b_i - a_i^T x^*}{a_i^T v}|$ ). Thus for  $x := x^* + \lambda v$  we have  $x \notin P$  because  $a_i^T x > b_i$ . This is a contradiction to the fact that P contains the line  $\{x \in \mathbb{R}^n : x = x^* + \lambda \cdot v, \ \lambda \in \mathbb{R}\}$ .

Thus the kernel of A is not empty, and A does not have full column rank.

Conversely, if A does not have full column rank, let  $x^*$  be some feasible point of the polyhedron, and let v be a nonzero vector from the kernel of A. Then  $x^* + \lambda \cdot v \in P$  for all  $\lambda \in \mathbb{R}$ . Hence P contains a line.

## Problem 3

Given  $x^* = (0\ 1\ 1)^T \in \mathbb{R}^3$  and the vector  $d = (1\ 1\ -1)^T \in \mathbb{R}^3$  decide if the ray  $\{x^* + \lambda d : \lambda \in \mathbb{R}_{\geq 0}\}$  intersects the following hyperplanes while moving in the direction of d. Give the order in which the trajectory passes the planes.

$$P_1 = \{x \in \mathbb{R}^3 : (1 \ 2 \ 3)x = 0\}$$

$$P_2 = \{x \in \mathbb{R}^3 : (3 \ 2 \ 1)x = 4\}$$

$$P_3 = \{x \in \mathbb{R}^3 : (1 \ 1 \ 1)x = 2\}$$

$$P_4 = \{x \in \mathbb{R}^3 : (0 \ 1 \ 3)x = -1\}$$

#### **Solution:**

The trajectory of  $x^*$  is given by the line  $\{x^* + \delta d : \delta \geq 0\}$  where a point in the trajectory moves further away from  $x^*$  if  $\delta$  becomes larger. To find the order in which  $x^*$  passes the planes we search the corresponding  $\delta_i$  for which  $x^* + \delta_i d$  is in the plane  $P_i$  or decide that such a  $\delta$  does not exist.

 $P_1$ :  $(1\ 2\ 3)((0\ 1\ 1)^T + \delta(1\ 1\ -1)^T) = 5 + 0 \cdot \delta = 5 \neq 0$  for all  $\delta$ , so  $x^*$  does not pass  $P_1$  since it moves parallel to it.

P<sub>2</sub>: 
$$(3\ 2\ 1)((0\ 1\ 1)^T + \delta(1\ 1\ -1)^T) = 3 + 4\delta = 4$$
 for  $\delta = \frac{1}{4}$ .  
P<sub>3</sub>:  $(1\ 1\ 1)((0\ 1\ 1)^T + \delta \cdot (1\ 1\ -1)^T) = 2 + \delta = 2$  for  $\delta = 0$ , so  $x^*$  is already on P<sub>3</sub>.  
P<sub>4</sub>:  $(0\ 1\ 3)((0\ 1\ 1)^T + \delta \cdot (1\ 1\ -1)^T) = 4 - 2\delta = -1$  for  $\delta = \frac{5}{2}$ .

The order in which  $x^*$  passes the planes is  $P_3$ ,  $P_2$ ,  $P_4$ . The plane  $P_1$  will never be passed.

#### Problem 4

Provide a proof or counterexample to the following statement:

Let  $\max\{c^T x : x \in \mathbb{R}^n, Ax \leq b\}$  be a linear program with  $A \in \mathbb{R}^{m \times n}$  of full column rank. If B is an optimal basis, then all the components of  $\lambda_B$  are strictly positive.

# Solution:

False. Consider the linear program

$$\max \quad x_1 + x_2$$
 subject to 
$$x_1 + x_2 \le 1$$
 
$$-x_1 \le 0$$
 
$$-x_2 \le 0$$

The feasible region of this LP is the triangle in  $\mathbb{R}^2$  with vertices (0,0), (1,0), and (0,1). An optimal basis is  $\{1,2\}$  with corresponding feasible basic solution (0,1). Here,

$$\lambda^{\mathrm{T}} \begin{bmatrix} 1 & 1 \\ -1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 \end{bmatrix}$$

which implies  $\lambda^{T} = \begin{bmatrix} 1 & 0 \end{bmatrix}$ .

## Problem 5

Consider the following LP:

- a) Given the basis  $B = \{1, 2, 6\}$ , compute  $x^*$  with  $A_B x^* = b_B$ .
- b) Decide whether  $x^*$  is feasible.
- c) Compute  $\lambda \in \mathbb{R}^3$  with  $\lambda^T A_B = c^T$ .
- d) Decide whether B is an optimal basis.

## **Solution:**

a) Calculate  $A_B^{-1}$  and write  $x^* = A_B^{-1} b_B$ 

$$x^* = \frac{1}{9} \begin{bmatrix} 6 & 3 & 6 \\ 1 & 2 & 7 \\ 0 & 0 & -9 \end{bmatrix} \begin{bmatrix} 3 \\ 5 \\ 0 \end{bmatrix} = \frac{1}{9} \begin{bmatrix} 33 \\ 13 \\ 0 \end{bmatrix}$$

b) For the feasibility of  $x^*$  it is sufficient to see if it fulfills all inequalities not in the basis, i.e. in the set  $\{3,4,5\}$ .

$$\frac{1}{9}(-33+3\cdot 13+2\cdot 0) = \frac{6}{9} \le 2 \tag{3}$$

$$\frac{1}{9}(-33+0+0) \le 0 \tag{4}$$

$$\frac{1}{9}(0 - 13 + 0) \le 0 \tag{5}$$

c) We reuse  $A_B^{-1}$  as calculated in a) to get the equation  $\lambda^T = c^T A_B^{-1}$ 

$$\lambda^{T} = \begin{bmatrix} 2 & 4 & 3 \end{bmatrix} \frac{1}{9} \begin{bmatrix} 6 & 3 & 6 \\ 1 & 2 & 7 \\ 0 & 0 & -9 \end{bmatrix} = \frac{1}{9} \begin{bmatrix} 16 & 14 & 13 \end{bmatrix}$$

d) B is optimal. To see this, extend the  $\lambda$  found in c) to a  $\lambda' \in \mathbb{R}^6$  by adding zeros to at the lines not in B. Now  $\lambda' \geq 0$  and it fulfills the equation  $\lambda' A = c^T$ . By Definition 4.3 of the lecture notes, B is an optimal basis.