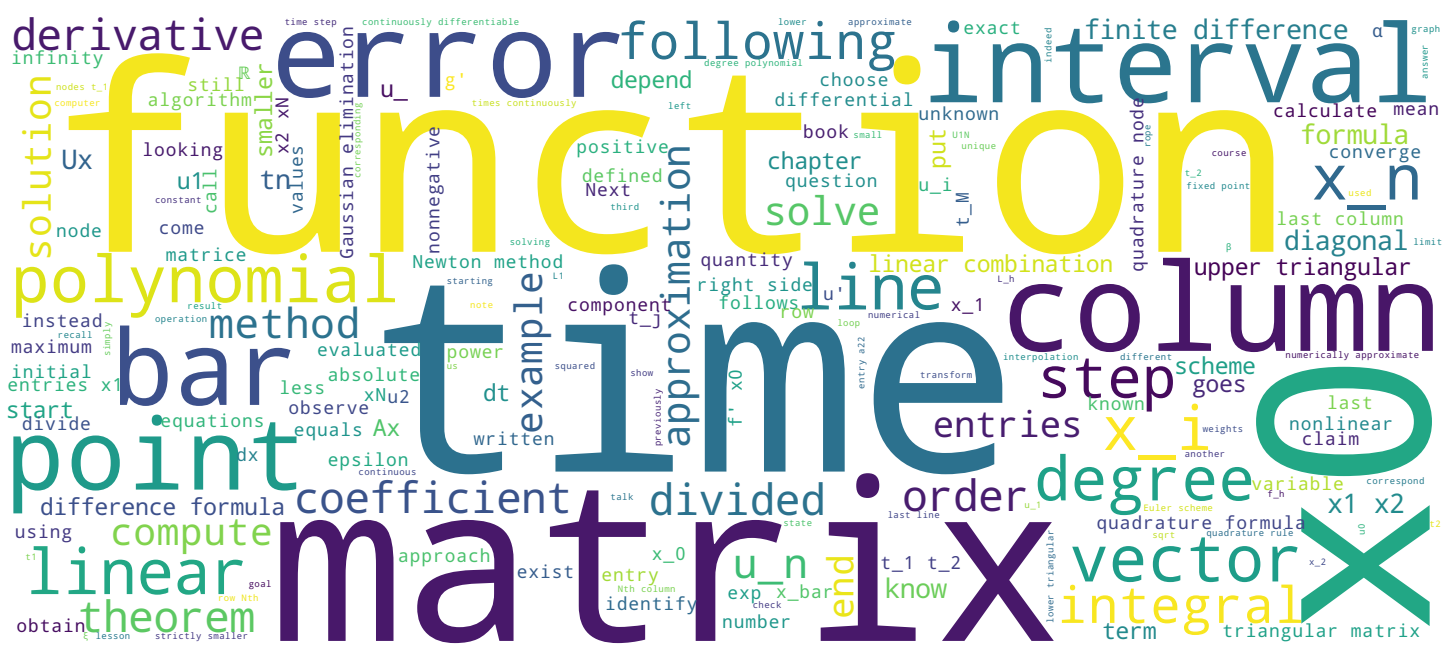


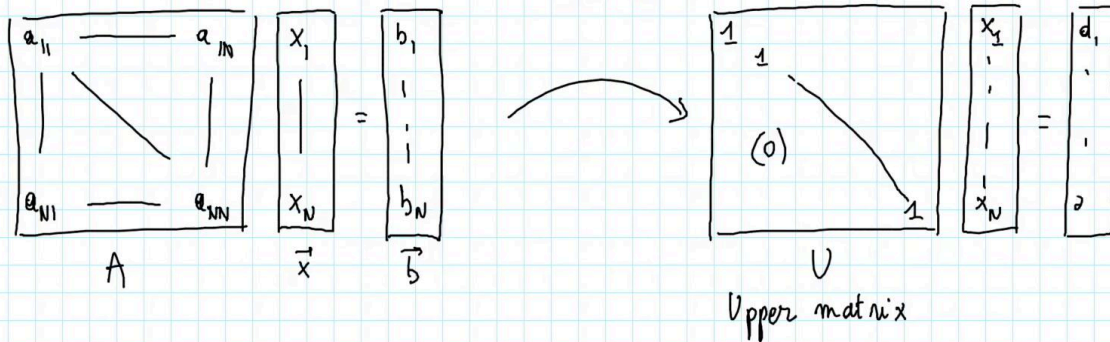
Chap 4: Elimination de Gauss - généralités



Video



Chap 4: Elimination de Gauss - généralités



We'll start this lesson by recalling Gaussian elimination, you have already introduced this method in your linear algebra course. We'll see this method again in a more algorithmic form. So we want to solve the linear system $Ax=b$ where A is a $N \times N$ matrix. Here is A , with N rows and N columns, its first entry is a_{11} and goes to a_{1N} , first row, N th column. Then we have the first column here, so the entries a_{11} to a_{N1} , and finally, at the last row, last column we have the coefficient a_{NN} . Here is our matrix A . I am looking for the unknown vector x such that $Ax=b$ with entries x_1, x_2, \dots, x_N , and b the right side of the equation with entries b_1, b_2, \dots, b_N . Here are x and b . The principle of Gaussian elimination is to transform the linear system making linear combinations of rows and columns, in a linear system that I'll write, a linear system with N lines and N columns, I'll call the matrix of the system, U . U stands for upper triangular matrix, this upper triangular matrix has 1's on its diagonal and 0 below. The solution of the linear system, is still the vector x with entries x_1, x_2, \dots, x_N , and the right side of the equation changed, I'll call it d , with entries d_1, d_2, \dots, d_N .

Notes

Summary



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$$\begin{array}{c}
 \begin{array}{|ccc|} \hline a_{11} & \dots & a_{1N} \\ \hline & \ddots & \\ \hline a_{N1} & \dots & a_{NN} \\ \hline \end{array} & \begin{array}{|c|} \hline x_1 \\ \hline \vdots \\ \hline x_N \\ \hline \end{array} & = & \begin{array}{|c|} \hline b_1 \\ \hline \vdots \\ \hline b_N \\ \hline \end{array} \\
 A & \vec{x} & & \vec{b}
 \end{array}
 \quad \rightarrow \quad
 \begin{array}{c}
 \begin{array}{|ccc|} \hline 1 & u_{12} & \dots & u_{1N} \\ \hline & 1 & & \\ \hline & & \ddots & \\ \hline & & & u_{N-1,N} \\ \hline & & & & 1 \\ \hline \end{array} & \begin{array}{|c|} \hline x_1 \\ \hline \vdots \\ \hline x_N \\ \hline \end{array} & = & \begin{array}{|c|} \hline d_1 \\ \hline \vdots \\ \hline d_N \\ \hline \end{array} \\
 U & \vec{x} & & \vec{d} \\
 \text{Upper matrix} & & &
 \end{array}$$

1^{ère} étape

$$\begin{array}{|c|} \hline 1 \\ \hline 0 \\ \hline \vdots \\ \hline 0 \\ \hline \end{array}$$

2^e étape

$$\begin{array}{|c|} \hline 1 \\ \hline 0 \\ \hline \vdots \\ \hline 0 \\ \hline \end{array}$$

N^e étape

$$\begin{array}{|c|} \hline 1 \\ \hline 0 \\ \hline \vdots \\ \hline 0 \\ \hline \end{array}$$

Here is d , and here is x . And the coefficients of the matrix U are U_{12} in first row, second column, until U_{1N} at the first row, Nth column and so on we have the entry $U_{(N-1)N}$. So the goal is starting with $Ax=b$ to end up with this system $Ux=d$ in N steps. The first step is as follows. Here is the matrix A , what we do is put a 1 here, instead of coefficient a_{11} , by simply dividing the line by the first entry a_{11} , provided it's nonzero, then we put a 0 here at the coefficient a_{21} , and so on on the first column, we do several operations to get zeroes on the first column. That's the first step. Then comes the second step, The matrix is basically the same except that we have 1, 0, 0,... on the first column so in the second step we'll put a 1 instead of the entry a_{22} , we'll do so by dividing the line by this entry a_{22} , then we'll make a linear combination of the second and third lines to get a zero here, and so on until the end of the second column, so that's the second step. And we can imagine that in the last step, the Nth one I will end up with a linear system $Ux=d$ as this one there, $Ux=d$. Thus, the matrix A was transformed in a matrix U with here 1, 0, 0,....

Notes

Summary



Chap 4: Elimination de Gauss - généralités

$$\begin{array}{c}
 \begin{array}{|c|c|c|} \hline a_{11} & \dots & a_{1N} \\ \hline & \ddots & \\ \hline a_{N1} & \dots & a_{NN} \\ \hline \end{array} & \begin{array}{|c|} \hline x_1 \\ \hline \vdots \\ \hline x_N \\ \hline \end{array} = \begin{array}{|c|} \hline b_1 \\ \hline \vdots \\ \hline b_N \\ \hline \end{array} \\
 A \quad \quad \quad \vec{x} \quad \quad \quad \vec{b}
 \end{array}
 \quad \rightarrow \quad
 \begin{array}{c}
 \begin{array}{|c|c|c|} \hline 1 & u_{12} & \dots & u_{1N} \\ \hline & 1 & & \\ \hline & & \ddots & \\ \hline & & & u_{N,N-1} \\ \hline & & & & 1 \\ \hline \end{array} & \begin{array}{|c|} \hline x_1 \\ \hline \vdots \\ \hline x_N \\ \hline \end{array} = \begin{array}{|c|} \hline d_1 \\ \hline \vdots \\ \hline d_N \\ \hline \end{array} \\
 U \quad \quad \quad \vec{x} \quad \quad \quad \vec{d} \\
 \text{Upper matrix} \quad \quad \quad \text{2}
 \end{array}$$

1^{ère} étape

$$\begin{array}{|c|c|c|} \hline 1 & & \\ \hline 0 & & \\ \hline \vdots & & \\ \hline 0 & & \\ \hline \end{array}$$

2^e étape

$$\begin{array}{|c|c|c|} \hline 1 & & \\ \hline 0 & 1 & \\ \hline \vdots & & \\ \hline 0 & & \\ \hline \end{array}$$

N^e étape

$$\begin{array}{|c|c|c|} \hline 1 & & \\ \hline 0 & 1 & \\ \hline \vdots & & \\ \hline 0 & & \\ \hline \end{array}
 \begin{array}{|c|c|} \hline 1 & \\ \hline 0 & 1 \\ \hline \end{array}$$

U

here 1,0,..., and 0 down here, until the end, at the last but one column we have 1, 0, and on the last column we have 1. So that's our matrix U, la matrice que vous obtenez du système linéaire $Ux = d$, that we now have to solve. Solving the linear system $Ux=d$ is easy simply because we start with the last line, and get $x_N=d_N$, then on the last but one line we get $x_{(N-1)}=d_{(N-1)}$ minus this term here, which is $u_{(N-1)N}$ times x_N , which we know and so on. So that solves easily our upper triangular linear system.

Notes

Summary

